



1021_HyperSizer-Methods-Approach-FBD Tab Matrix Math.ppt

**Collier Research Corporation
Hampton, VA**

Objective



- ❑ 1st glimpse of HyperSizer Basic
- ❑ Get familiar with ABD matrix computations

Objective



- ❑ 1st glimpse of HyperSizer Basic
- ❑ Get familiar with ABD matrix computations
- ❑ Why?
 - ❑ HyperSizer smeared stiffness formulation



Outline



- ❑ HyperSizer panel stiffness approach

- ❑ Isotropic plate stiffness relations

- ❑ Metallic sheet examples
 - ❑ Mechanical loads
 - ❑ Thermal loads
 - ❑ Superimposed pressure





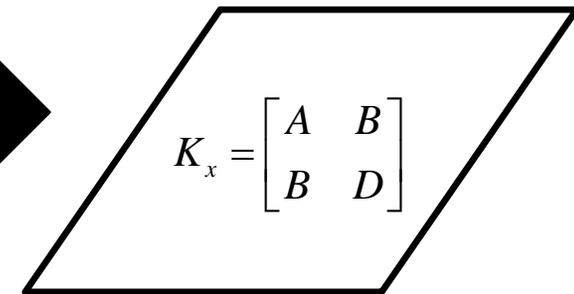
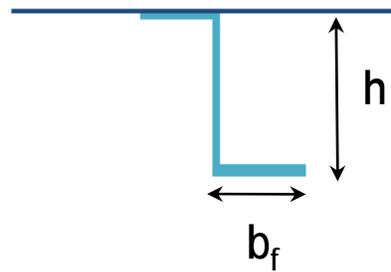
Panel Stiffness Approach

Panel Stiffness - Technical Approach



Local Stiffness

Global Stiffness



"smeared stiffness"

[45/90/90/-45/0/0/90/0]s

Panel Stiffness – Technical Approach



- Stiffened panel constitutive equation
 - [A] → membrane
 - [D] → bending
 - [B] → membrane-bending coupling

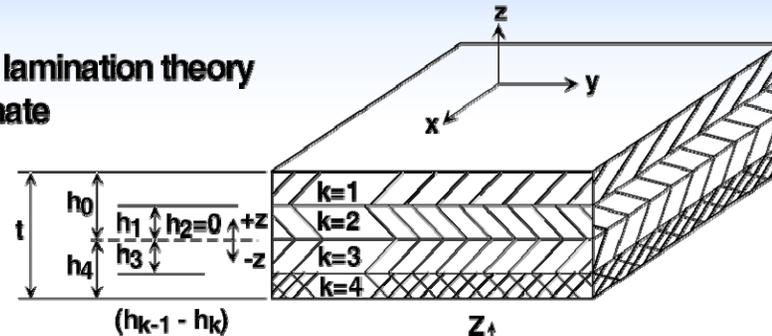
$$\begin{bmatrix} \vec{N} \\ \vec{M} \end{bmatrix} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{bmatrix} \begin{bmatrix} \vec{\varepsilon} \\ \vec{\kappa} \end{bmatrix} - \begin{bmatrix} \vec{N}^T \\ \vec{M}^T \end{bmatrix}$$

Panel Stiffness - Technical Approach

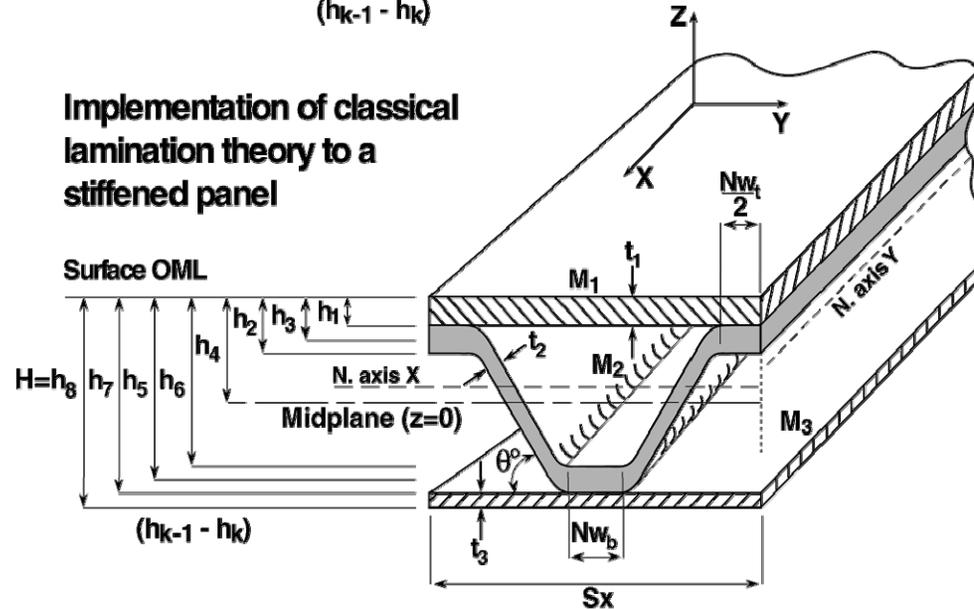


- Classical Lamination Theory extended to a represent any stiffened cross sectional shape

Classical lamination theory of a laminate



Implementation of classical lamination theory to a stiffened panel



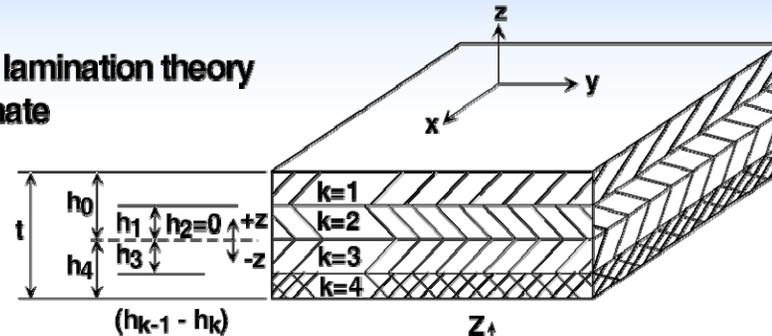
ILMNT FRMLTN(2)vertl Collier

Panel Stiffness - Technical Approach

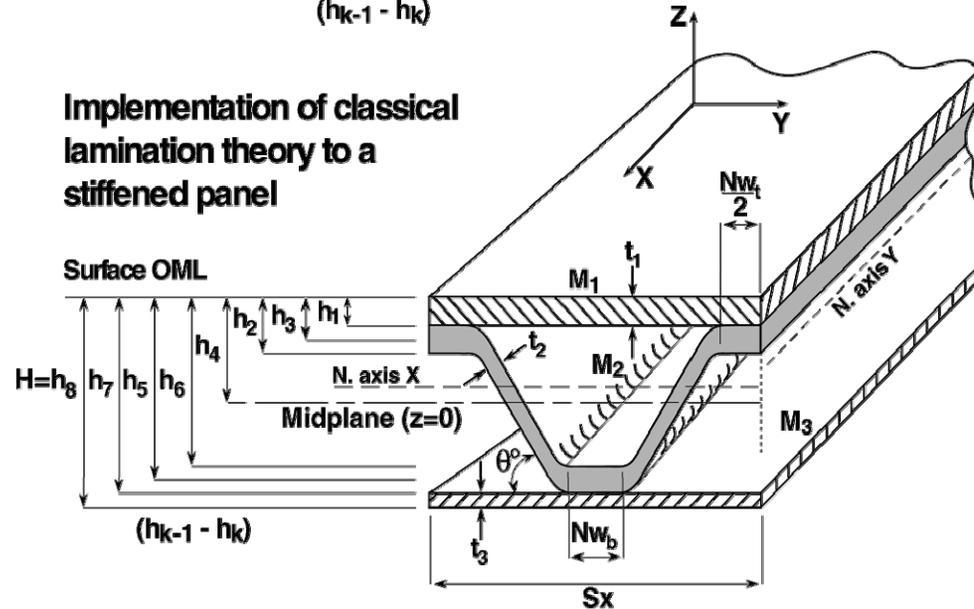


- Classical Lamination Theory extended to a represent any stiffened cross sectional shape
- General panel behaviors, are quantified with:
 - Stiffness terms [A], [B], [D]
 - Thermal coefficients [A^α], [B^α], [D^α]

Classical lamination theory of a laminate

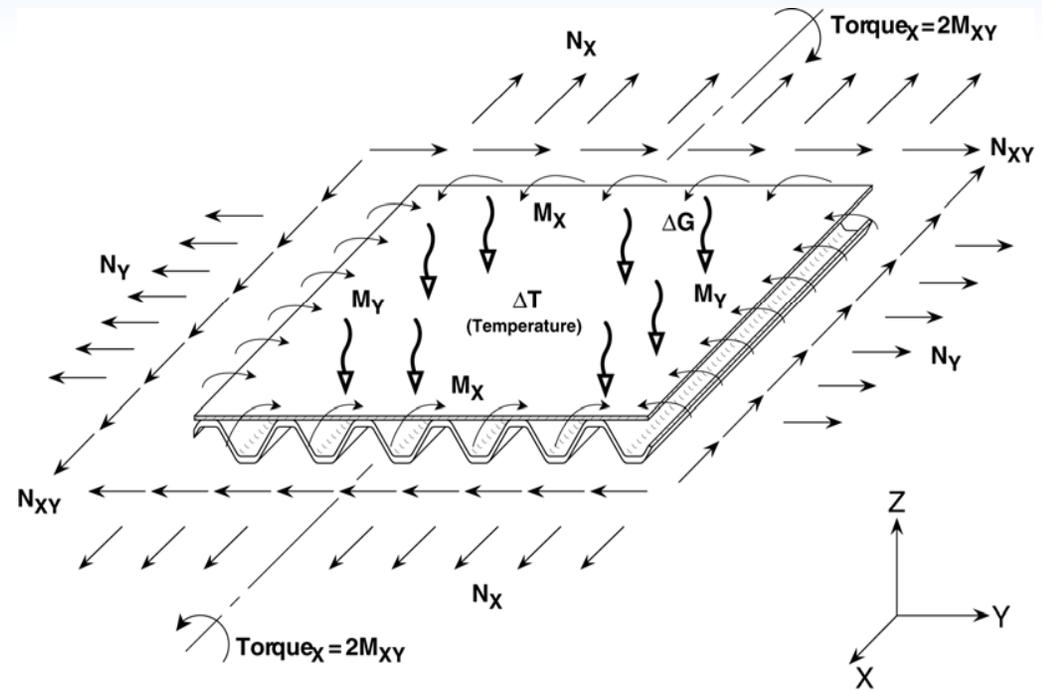


Implementation of classical lamination theory to a stiffened panel



ILMNT FRMLTN(2)vertl Collier

Free Body Diagram (FBD)



IST-SZICollier

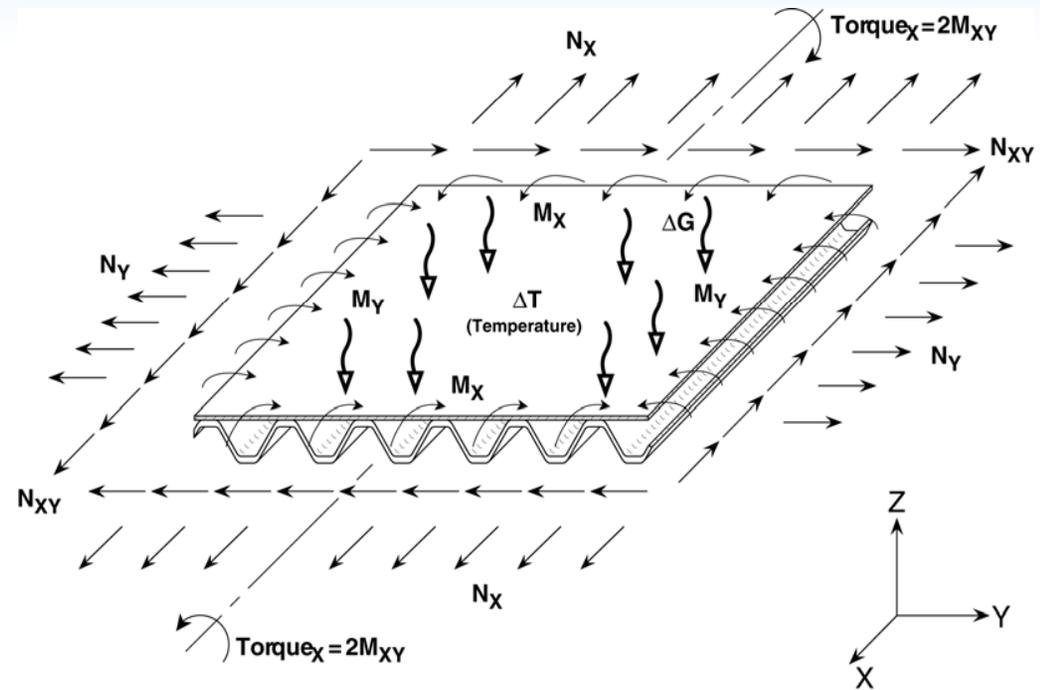
Thermoelastic Formulations



Free Body Diagram (FBD)



- **Balanced free-body loads**
 - FEA
 - User-defined input



IST-SZICollier

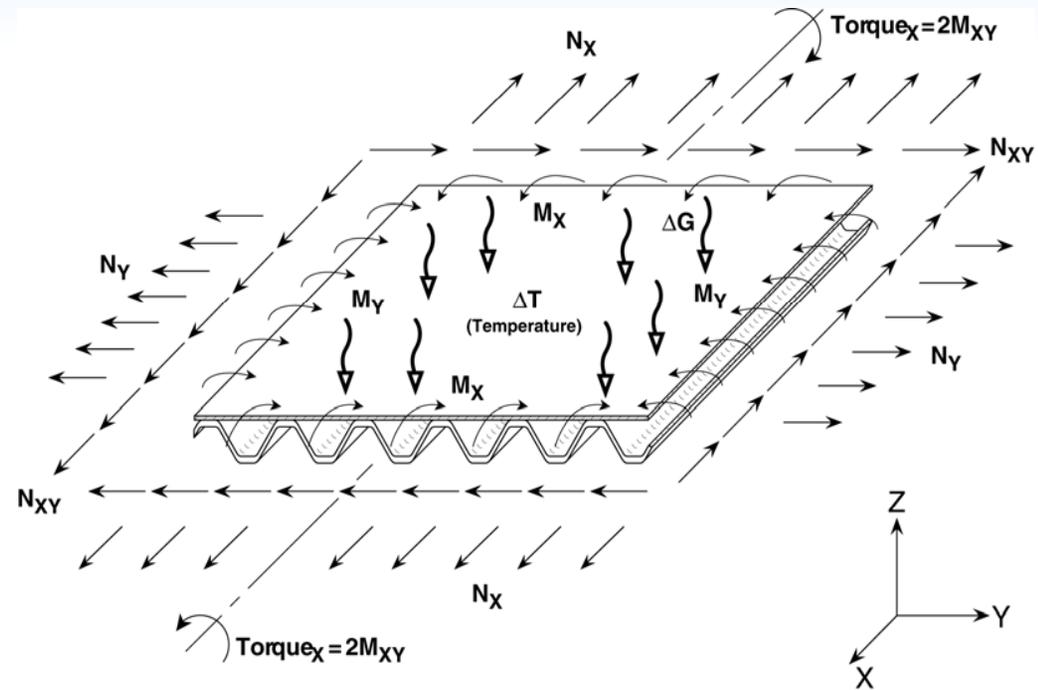
Thermoelastic Formulations



Free Body Diagram (FBD)



- **Balanced free-body loads**
 - FEA
 - User-defined input
- **Consistently applied thermoelastic formulations guarantee**
 - Equilibrium of forces



IST-SZICollier

Thermoelastic Formulations





Isotropic Plate Stiffness Relations

Isotropic Plate Stiffness



Plane Stress Constitutive Equations

□ Compliance

$$\begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix} = \begin{bmatrix} \frac{1}{E} & \frac{-\nu}{E} & 0 \\ \frac{-\nu}{E} & \frac{1}{E} & 0 \\ 0 & 0 & \frac{1}{G_{12}} \end{bmatrix} \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix}$$

Isotropic Plate Stiffness



Plane Stress Constitutive Equations

□ Compliance

$$\begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix} = \begin{bmatrix} \frac{1}{E} & \frac{-\nu}{E} & 0 \\ \frac{-\nu}{E} & \frac{1}{E} & 0 \\ 0 & 0 & \frac{1}{G_{12}} \end{bmatrix} \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix}$$



□ Stiffness

$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} \frac{E}{1-\nu^2} & \frac{\nu E}{1-\nu^2} & 0 \\ \frac{\nu E}{1-\nu^2} & \frac{E}{1-\nu^2} & 0 \\ 0 & 0 & G_{12} \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix}$$

Isotropic Plate Stiffness



Plane Stress Constitutive Equations

□ Compliance

$$\begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix} = \begin{bmatrix} \frac{1}{E} & \frac{-\nu}{E} & 0 \\ \frac{-\nu}{E} & \frac{1}{E} & 0 \\ 0 & 0 & \frac{1}{G_{12}} \end{bmatrix} \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix}$$



□ Stiffness

$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} \frac{E}{1-\nu^2} & \frac{\nu E}{1-\nu^2} & 0 \\ \frac{\nu E}{1-\nu^2} & \frac{E}{1-\nu^2} & 0 \\ 0 & 0 & G_{12} \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix}$$

Poisson term
for plates

$$\frac{1}{1-\nu^2}$$



ABD Matrix of Isotropic Plate



$$\begin{bmatrix} N_x \\ N_y \\ N_s \\ M_x \\ M_y \\ M_s \end{bmatrix} = \begin{bmatrix} \frac{Et}{1-\nu^2} & \frac{\nu Et}{1-\nu^2} & 0 & 0 & 0 & 0 \\ \frac{\nu Et}{1-\nu^2} & \frac{Et}{1-\nu^2} & 0 & 0 & 0 & 0 \\ 0 & 0 & Gt & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{Et^3}{12(1-\nu^2)} & \frac{\nu Et^3}{12(1-\nu^2)} & 0 \\ 0 & 0 & 0 & \frac{\nu Et^3}{12(1-\nu^2)} & \frac{Et^3}{12(1-\nu^2)} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{Gt^3}{12} \end{bmatrix} \begin{bmatrix} \epsilon_x^o \\ \epsilon_y^o \\ \gamma_{xy}^o \\ \kappa_x \\ \kappa_y \\ \kappa_z \end{bmatrix}$$

ABD Matrix of Isotropic Plate



$$\begin{bmatrix} N_x \\ N_y \\ N_s \\ M_x \\ M_y \\ M_s \end{bmatrix} = \begin{bmatrix} \frac{Et}{1-\nu^2} & \frac{\nu Et}{1-\nu^2} & 0 & 0 & 0 & 0 \\ \frac{\nu Et}{1-\nu^2} & \frac{Et}{1-\nu^2} & 0 & 0 & 0 & 0 \\ 0 & 0 & Gt & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{Et^3}{12(1-\nu^2)} & \frac{\nu Et^3}{12(1-\nu^2)} & 0 \\ 0 & 0 & 0 & \frac{\nu Et^3}{12(1-\nu^2)} & \frac{Et^3}{12(1-\nu^2)} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{Gt^3}{12} \end{bmatrix} \begin{bmatrix} \epsilon_x^o \\ \epsilon_y^o \\ \gamma_{xy}^o \\ \kappa_x \\ \kappa_y \\ \kappa_z \end{bmatrix}$$

ABD Matrix of Isotropic Plate



Membrane

$$A_{11} = A_{22} = \frac{Et}{1-\nu^2}$$

$$A_{12} = A_{21} = A_{11}\nu$$

$$A_{11}^{-1} = A_{22}^{-1} = \frac{1}{Et}$$

$$A_{12}^{-1} = A_{21}^{-1} = -A_{11}^{-1}\nu$$

Bending

$$D_{11} = D_{22} = \frac{Et^3}{12(1-\nu^2)}$$

$$D_{12} = D_{21} = D_{11}\nu$$

$$D_{11}^{-1} = D_{22}^{-1} = \frac{12}{Et^3}$$

$$D_{12}^{-1} = D_{21}^{-1} = -D_{11}^{-1}\nu$$



Examples

Isotropic Plate Force and Moment Exercises



Perform several exercises to verify the physics of the ABD matrix in using HyperSizer's operation user-defined loads

- Specified Strain
- Specified Force
- Uniform ΔT
- Through-Thickness ΔT
- Pressure



Set up for Demo Problem



Copy an Isotropic: 'AL 7075' and rename to 'FBD Example'

Set properties

$$E_c = E_t = 10 \text{ Msi}$$

$$G = 3.846154 \text{ Msi}$$

$$\nu = 0.3$$

$$\alpha = 12^{-6}$$

Setup Group sizing bounds thickness equal to .1"

Set Ultimate Load Factor = 1.0



Examples with Isotropic Plates



Isotropic Plate

$$E = 10 \text{ Msi}$$

$$\nu = 0.3$$

$$G = 3.846154 \text{ Msi}$$

$$\text{Plate Thickness, } t = 0.1''$$

$$\text{CTE, } \alpha = 12 \mu\text{in/in}$$

Membrane

$$A_{11} = \frac{Et}{1-\nu^2} = \frac{(10)(0.1)}{0.91}$$

$$= 1.0989 \times 10^6 \text{ lb/in}$$

Bending

$$D_{11} = \frac{Et^3}{12(1-\nu^2)} = \frac{(10)(0.1)^3}{12(0.91)}$$

$$= 915.8 \text{ lb/in}$$



The Free Body Diagram Tab



- Entry of Loads and Boundary Conditions

Concepts Variables	Design-to Loads FBD	Failure Object Loads	Buckling Computed Properties	Notes Options
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Input (Per Load Case)

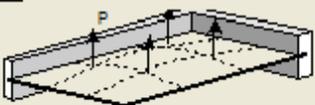
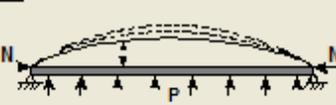
ULTIMATE-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101" Ref Temp:
 Thermal Load Set #201 "Load Set 201" Pressure: Temp:
 FEA Loads - Projects Only TT Grad:

	Nx,ex	Ny,ey	Nxy,xy	Mx,ex	My,ey	Mxy,xy	Qx	Qy
Applied Unit Value	Load	Load	Load	Constraine	Constraine	Constraine	Load	Load
For Strength Analysis	Free							
For Buckling Analysis	Constrained							
	Load							
	Deformation							

Superimposed Loads

Panel Pressure Beam-Column Moments

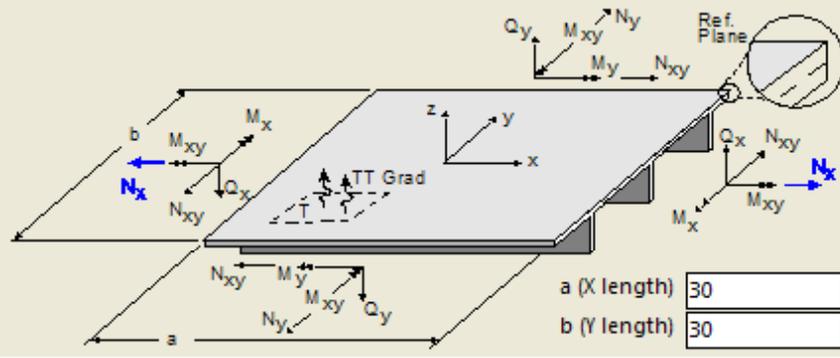



Initial Imperfection:

Zero Out FEA Computed Moments FIXED Boundary Condition

	Mx	My	Qx	Qy
MidSpan	0	0	0	0
EdgeCntr	0	0	0	0

Point Free Body Diagram (Constant Forces)



a (X length)
 b (Y length)

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx,ex	Ny,ey	Nxy,xy	Mx,ex	My,ey	Mxy,xy	Qx	Qy
Virtual Loads								
Design-to Loads								
Design-to Deformation	0	0	0	0	0	0		



Ex 1 – Applied ϵ_x , Constrained ϵ_y



Input (Per Load Case)

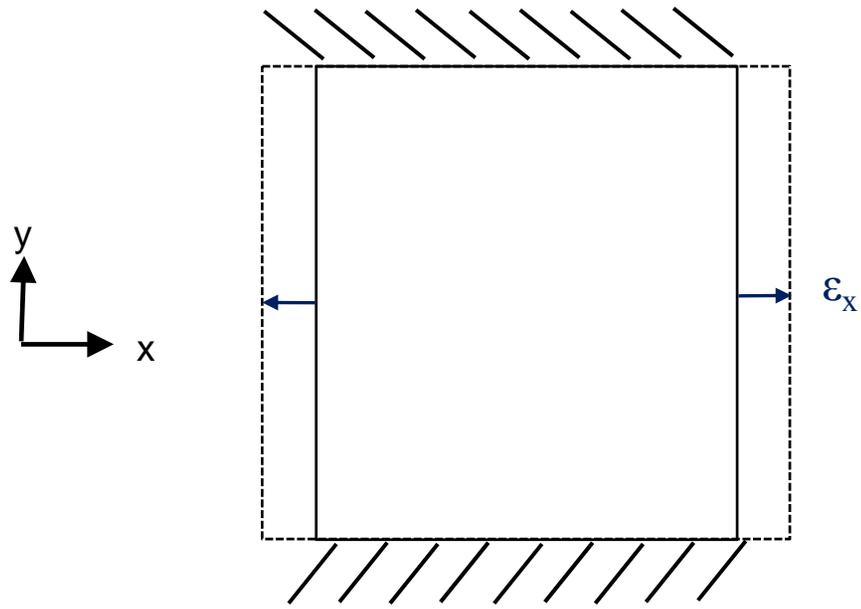
LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101" Ref Temp Temp
 Thermal Load Set #201 "Load Set 201" Pressure TT Grad

FEA Loads - Projects Only

User Loads Applied Unit Value

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
For Strength Analysis	Deformati	Constrain	Constrain	Constrain	Constrain	Constrain	Load	Load
For Buckling Analysis	0.001							
	0.001							



What will the loads look like?
Positive, negative or zero?

Ex 1 – Applied ϵ_x , Constrained ϵ_y



Input (Per Load Case)

LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101" Ref Temp Temp
 Thermal Load Set #201 "Load Set 201" Pressure TT Grad

FEA Loads - Projects Only

User Loads Applied Unit Value

	Nx,εx	Ny,εy	Nxy,γxy	Mx,εx	My,εy	Mxy,εxy	Qx	Qy
For Strength Analysis	0.001							
For Buckling Analysis	0.001							

$$N_x = A_{11}\epsilon_x + A_{12}\cancel{\epsilon_y}$$

$$= (1.0989 \times 10^6)(0.001)$$

$$= 1098.9$$

Set Ultimate Factor = 1.0

$$N_y = A_{21}\epsilon_x = \nu A_{11}\epsilon_x$$

$$= (0.3)(1.0989 \times 10^6)(0.001)$$

$$= 329.67$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: STRENGTH

	Nx,εx	Ny,εy	Nxy,γxy	Mx,εx	My,εy	Mxy,εxy	Qx	Qy
Virtual Loads	1098.9	329.67	0	0	0	0	0	0
Design-to Loads	1098.9	329.67	0	0	0	0	0	0
Design-to Deformation	0.001	0	0	0	0	0		



Ex 2 – Applied N_x , Free N_y



Input (Per Load Case)

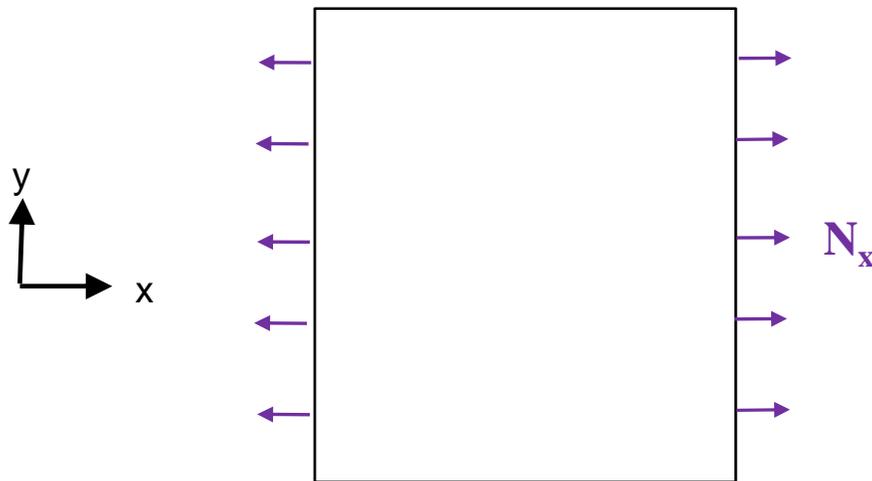
LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101" Ref Temp Temp
 Thermal Load Set #201 "Load Set 201" Pressure TT Grad

FEA Loads - Projects Only

User Loads Applied Unit Value For Strength Analysis For Buckling Analysis

	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, ϵ_x	M_y, ϵ_y	M_{xy}, ϵ_{xy}	Q_x	Q_y
Applied Unit Value	Load	Free	Constraine	Constraine	Constraine	Constraine	Load	Load
For Strength Analysis	1000							
For Buckling Analysis	1000							



What will the strains look like?

Ex 2 – Applied N_x , Free N_y



Input (Per Load Case)

LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, ϵ_x	M_y, ϵ_y	M_{xy}, ϵ_{xy}	Q_x	Q_y
Load	1000	Free	Constrained	Constrained	Constrained	Constrained	Load	Load
Applied Unit Value	1000							

$$\epsilon_x = A_{11}^{-1} N_x + A_{12}^{-1} N_y \quad A_{11}^{-1} = \frac{1}{Et}$$

$$= \frac{1}{(10)(.1)} (1000) = 0.001$$

$$\epsilon_y = A_{21}^{-1} N_x + A_{22}^{-1} N_y \quad A_{21}^{-1} = \frac{-\nu}{Et}$$

$$= \frac{-(0.3)}{(10)(.1)} (1000) = -0.0003$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: STRENGTH

	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, ϵ_x	M_y, ϵ_y	M_{xy}, ϵ_{xy}	Q_x	Q_y
Virtual Loads								
Design-to Loads	1000	0	0	0	0	0	0	0
Design-to Deformation	0.001	-2.999999E-04	0	0	0	0		



Ex 3 – Applied κ_x , Constrained κ_y



Input (Per Load Case)

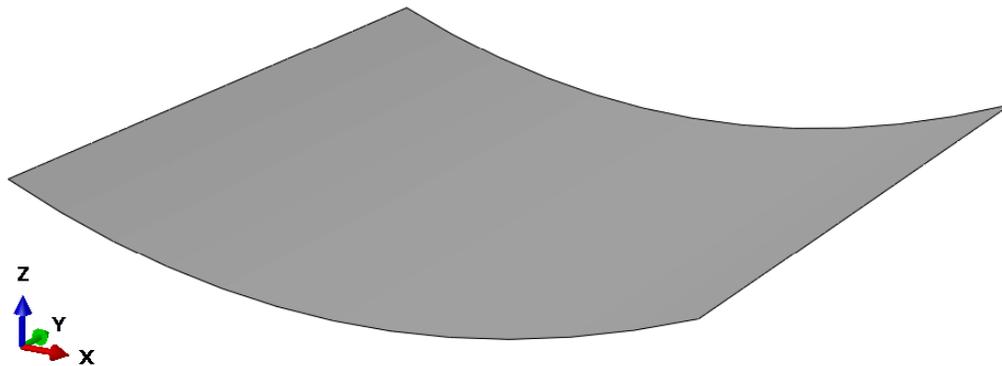
LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101" Ref Temp Temp
 Thermal Load Set #201 "Load Set 201" Pressure TT Grad

FEA Loads - Projects Only

User Loads Applied Unit Value For Strength Analysis For Buckling Analysis

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, κ_x	My, κ_y	Mxy, κ_{xy}	Qx	Qy
	Free	Free	Constraine	Deformatic	Constraine	Constraine	Load	Load
				0.01				
				0.01				



What will the loads look like?

Ex 3 – Applied κ_x , Constrained κ_y



Input (Per Load Case)

LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

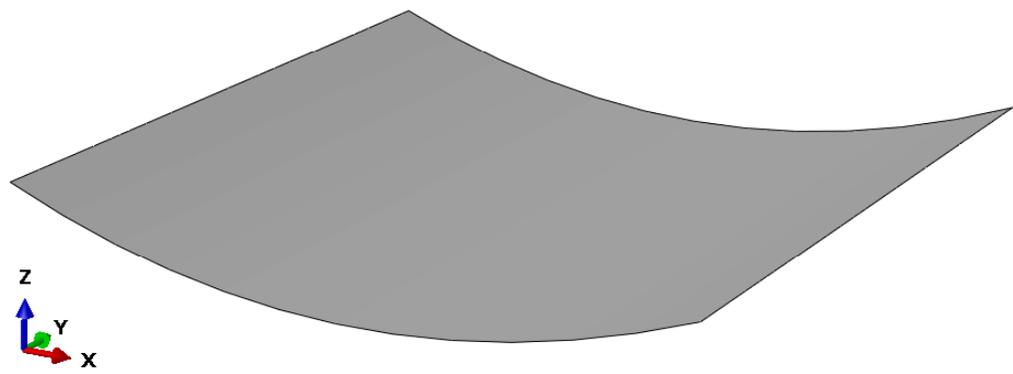
Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

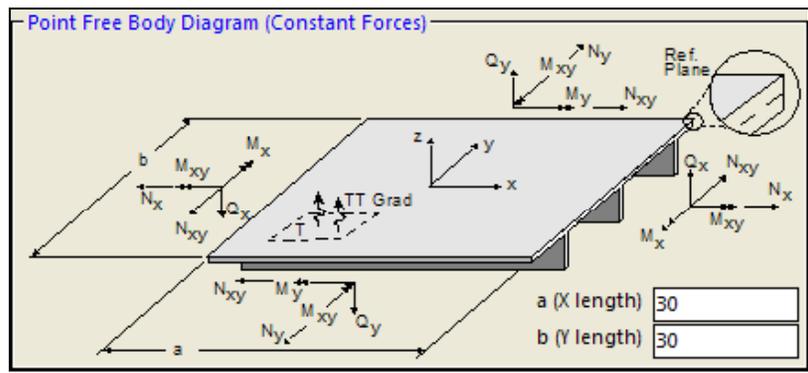
For Strength Analysis
 For Buckling Analysis

	Nx,ex	Ny,ey	Nxy,xyx	Mx,ix	My,iy	Mxy,ixy	Qx	Qy
	Free	Free	Constraine	Deformatic	Constraine	Constraine	Load	Load
				0.01				
				0.01				

Ref Temp: Temp:
 Pressure: TT Grad:



What will the loads look like?



Ex 3 – Applied κ_x Constrained κ_y



Input (Per Load Case)

LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads

Applied Unit Value	Nx,εx	Ny,εy	Nxy,γxy	Mx,εx	My,εy	Mxy,εxy	Qx	Qy
For Strength Analysis	Free	Free	Constraine	Deformatic	Constraine	Constraine	Load	Load
For Buckling Analysis				0.01				
				0.01				

$$\begin{aligned}
 Mx &= D_{11}\kappa_x + D_{12}\cancel{\kappa_y} \\
 &= (915.8)(0.01) \\
 &= 9.158
 \end{aligned}$$

$$\begin{aligned}
 My &= D_{21}\kappa_x = \nu D_{11}\kappa_x \\
 &= (0.3)(915.8)(0.01) \\
 &= 2.747
 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: STRENGTH

	Nx,εx	Ny,εy	Nxy,γxy	Mx,εx	My,εy	Mxy,εxy	Qx	Qy
Virtual Loads	0	0	0	9.15751	2.74725	0	0	0
Design-to Loads	0	0	0	9.15751	2.74725	0	0	0
Design-to Deformation	0	0	0	0.01	0	0		



Ex 4 – Applied M_x , Free M_y



Input (Per Load Case)

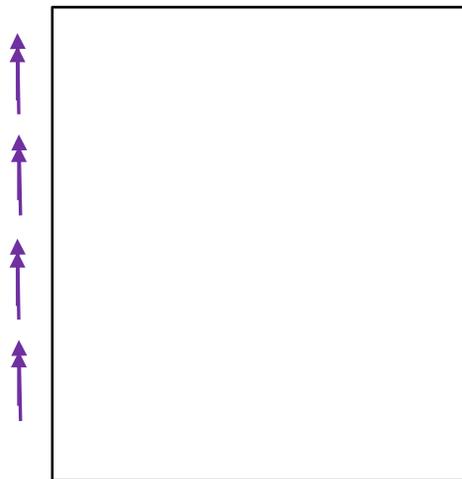
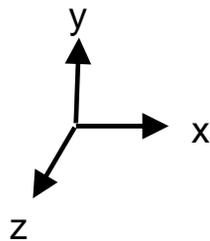
LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101" Ref Temp Temp
 Thermal Load Set #201 "Load Set 201" Pressure 0 TT Grad

FEA Loads - Projects Only

User Loads Applied Unit Value For Strength Analysis For Buckling Analysis

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, κ_x	My, κ_y	Mxy, κ_{xy}	Qx	Qy
	Free	Free	Free	Load	Free	Constraine	Load	Load
				100				
				100				



What will the strains look like?

M_x

Ex 4 – Applied M_x , Free M_y



Input (Per Load Case)

LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

	Nx,εx	Ny,εy	Nxy,γxy	Mx,εx	My,εy	Mxy,εxy	Qx	Qy
	Free	Free	Free	Load	Free	Constrained	Load	Load
				100				
				100				

$$\kappa_x = D_{11}^{-1}M_x + D_{12}^{-1}M_y \quad D_{11}^{-1} = \frac{12}{Et^3}$$

$$= \frac{12}{(10 \times 10^6)(.1)^3} (100) = 0.12$$

$$\kappa_y = D_{21}^{-1}M_x + D_{22}^{-1}M_y \quad D_{21}^{-1} = \frac{-12\nu}{Et^2}$$

$$= \frac{-12(0.3)}{(10 \times 10^6)(.1)^3} (100) = -0.036$$

Free Body Diagram Output (Controlling Factored Loadcase)

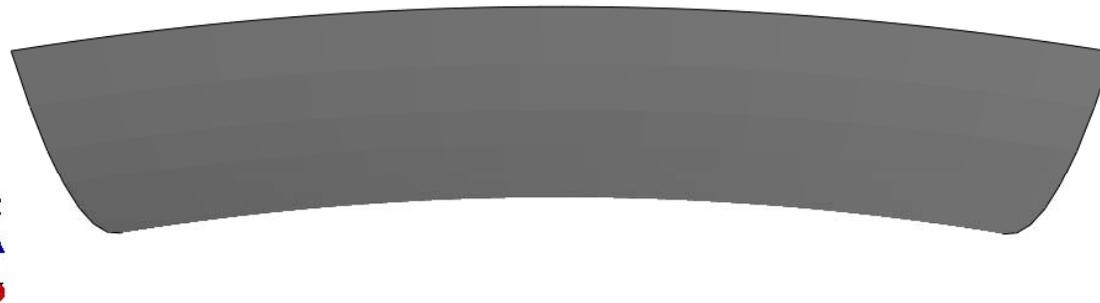
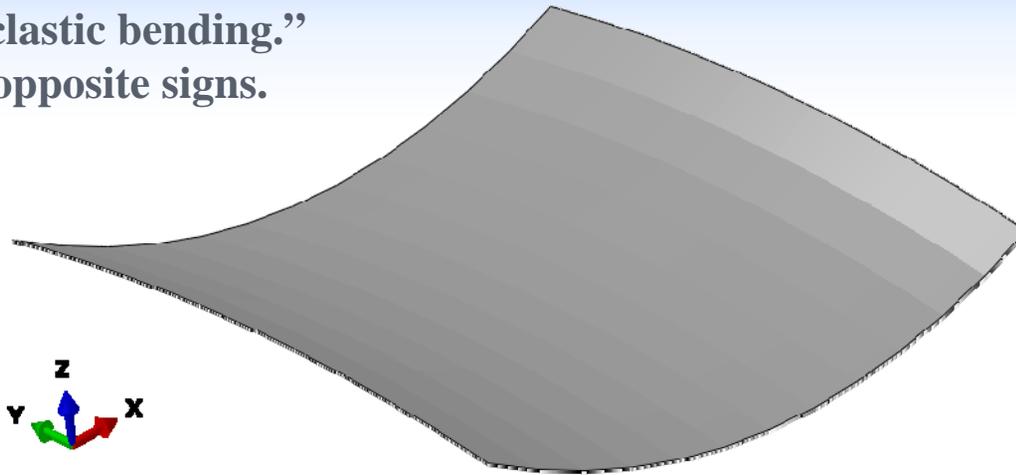
Controlling Analysis Load: STRENGTH

	Nx,εx	Ny,εy	Nxy,γxy	Mx,εx	My,εy	Mxy,εxy	Qx	Qy
Virtual Loads								
Design-to Loads	0	0	0	100	0	0	0	0
Design-to Deformation	0	0	0	0.12	-3.599999E-02	0		

Ex 4 – Applied M_x , Free M_y



Example of “anticlastic bending.”
Curvatures have opposite signs.



Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: STRENGTH

	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, ϵ_x	M_y, ϵ_y	M_{xy}, ϵ_{xy}	Q_x	Q_y
Virtual Loads								
Design-to Loads	0	0	0	100	0	0	0	0
Design-to Deformation	0	0	0	0.12	-3.599999E-02	0		

Ex 5 – Thermal: Applied ΔT Constrained



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"

Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only

User Loads Applied Unit Value

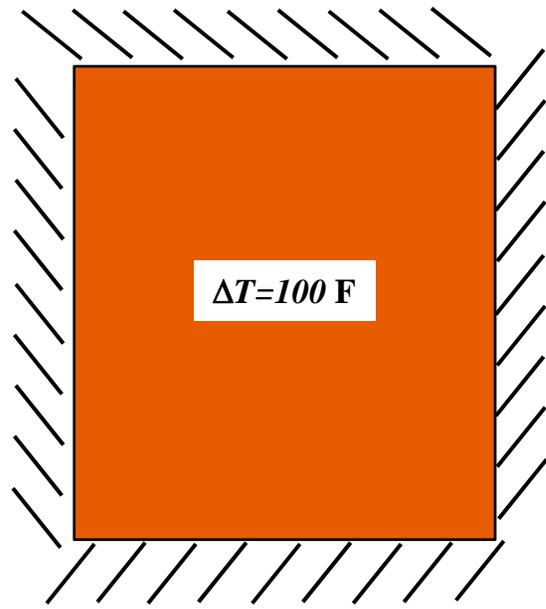
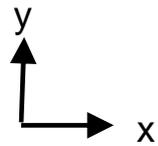
For Strength Analysis

For Buckling Analysis

Nx, ex	Ny, ey	Nxy, γ_{xy}	Mx, ix	My, iy	Mxy, ixy	Qx	Qy
Constrained	Constrained	Constrained	Constrained	Constrained	Constrained	Load	Load

Ref Temp 100 Temp 200

Pressure TT Grad 0



What will the loads look like?
Positive, negative or zero?

Ex 5 –Thermal: Applied ΔT Constrained

Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads

Applied Unit Value

For Strength Analysis

For Buckling Analysis

Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Constrained	Constrained	Constrained	Constrained	Constrained	Constrained	Load	Load

Ref Temp: 100 Temp: 200
 Pressure: TT Grad: 0

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Virtual Loads	-1714.29	-1714.29	0	0	0	0	0	0
Design-to Loads	-1714.29	-1714.29	0	0	0	0	0	0
Design-to Deformation	-0.0012	-0.0012	0	0	0	0		

Ex 5 –Thermal: Applied ΔT Constrained



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"
 FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

Ref Temp: 100 Temp: 200
 Pressure: TT Grad: 0

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Constrained	Constrained	Constrained	Constrained	Constrained	Constrained	Constrained	Load	Load

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Virtual Loads	-1714.29	-1714.29	0	0	0	0	0	0
Design-to Loads	-1714.29	-1714.29	0	0	0	0	0	0
Design-to Deformation	-0.0012	-0.0012	0	0	0	0		



Ex 5 –Thermal: Applied ΔT Constrained



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads

Applied Unit Value:
 For Strength Analysis:
 For Buckling Analysis:

Ref Temp:
 Temp:
 Pressure:
 TT Grad:

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Constrained	Constrained	Constrained	Constrained	Constrained	Constrained	Constrained	Load	Load

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Strain Actual (Computed Properties Tab)

Deformation

Strain X	<input type="text"/>	<input type="text" value="0"/>
Strain Y	<input type="text"/>	<input type="text" value="0"/>

Design-To Strain

$$\begin{aligned} \epsilon_x^{Design-To} &= \cancel{\epsilon_x^{Actual}} - \epsilon_x^T \\ &= -0.0012 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Virtual Loads	-1714.29	-1714.29	0	0	0	0	0	0
Design-to Loads	-1714.29	-1714.29	0	0	0	0	0	0
Design-to Deformation	-0.0012	-0.0012	0	0	0	0		



Ex 5 –Thermal: Applied ΔT Constrained



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Constrained	Constrained	Constrained	Constrained	Constrained	Constrained	Load	Load

Ref Temp: 100 Temp: 200
 Pressure: TT Grad: 0

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Strain Actual (Computed Properties Tab)

Deformation	
Strain X	0
Strain Y	0

Design-To Strain

$$\begin{aligned} \epsilon_x^{Design-To} &= \cancel{\epsilon_x^{Actual}} - \epsilon_x^T \\ &= -0.0012 \end{aligned}$$

Design-To Force

$$\begin{aligned} N_x^{Design-To} &= A_{11} \epsilon_x^{Design-To} + A_{12} \epsilon_y^{Design-To} \\ &= (1.0989 \times 10^6)(-0.0012) + (0.3)(1.0989 \times 10^6)(-0.0012) \\ &= -1714.3 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Virtual Loads	-1714.29	-1714.29	0	0	0	0	0	0
Design-to Loads	-1714.29	-1714.29	0	0	0	0	0	0
Design-to Deformation	-0.0012	-0.0012	0	0	0	0		



Ex 6 – Thermal: Applied ΔT , Edges Free



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"

Thermal Load Set #201 "Load Set 201"

Ref Temp 100 Temp 200

Pressure TT Grad 0

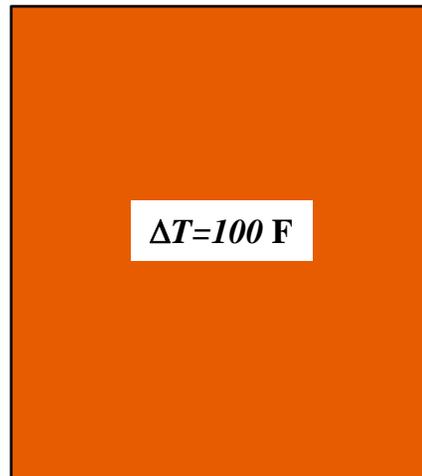
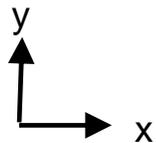
FEA Loads - Projects Only

User Loads Applied Unit Value

Nx, sx	Ny, sy	Nbz, ybz	Mx, sx	My, sy	Mbz, ybz	Qx	Qy
Free	Free	Free	Free	Free	Free	Load	Load

For Strength Analysis

For Buckling Analysis



What will the loads look like?
Positive, negative or zero?

Ex 6 –Thermal: Applied ΔT Free



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

Ref Temp Temp
 Pressure TT Grad

FEA Loads - Projects Only
 User Loads Applied Unit Value

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
For Strength Analysis	Free	Free	Free	Free	Free	Free	Load	Load
For Buckling Analysis								

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Virtual Loads								
Design-to Loads								
Design-to Deformation	0	0	0	0	0	0		



Ex 6 –Thermal: Applied ΔT Free



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

Ref Temp	100	Temp	200
Pressure		TT Grad	0
Nx, ϵ_x	Free	Ny, ϵ_y	Free
Nxy, γ_{xy}	Free	Mx, ϵ_x	Free
My, ϵ_y	Free	Mxy, ϵ_{xy}	Free
Qx	Load	Qy	Load

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Virtual Loads								
Design-to Loads								
Design-to Deformation	0	0	0	0	0	0		



Ex 6 –Thermal: Applied ΔT Free



Input (Per Load Case)

***ULTIMATE-THERMAL** Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

Ref Temp Temp
 Pressure TT Grad

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
<input checked="" type="radio"/> User Loads Applied Unit Value	Free	Free	Free	Free	Free	Free	Load	Load
For Strength Analysis								
For Buckling Analysis								

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Strain Actual (Computed Properties Tab)

Deformation	
Strain X	<input type="text" value="0.0012"/>
Strain Y	<input type="text" value="0.0012"/>

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Virtual Loads								
Design-to Loads								
Design-to Deformation	0	0	0	0	0	0		



Ex 6 –Thermal: Applied ΔT Free



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

Ref Temp	100	Temp	200
Pressure		TT Grad	0
Nx, ϵ_x	Free	Ny, ϵ_y	Free
Nxy, γ_{xy}	Free	Mx, ϵ_x	Free
My, ϵ_y	Free	Mxy, ϵ_{xy}	Free
Qx	Load	Qy	Load

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Strain Actual (Computed Properties Tab)

Deformation	
Strain X	0.0012
Strain Y	0.0012

Design-To Strain

$$\begin{aligned} \epsilon_x^{Actual} &= \epsilon_x^T \\ \epsilon_x^{Design-To} &= \epsilon_x^{Actual} - \epsilon_x^T \\ &= 0.0 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Virtual Loads								
Design-to Loads								
Design-to Deformation	0	0	0	0	0	0		



Ex 6 –Thermal: Applied ΔT Free



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

Ref Temp: 100 Temp: 200
 Pressure: TT Grad: 0

	Nx,xx	Ny,yy	Nxy,xy	Mx,xx	My,yy	Mxy,xy	Qx	Qy
<input checked="" type="radio"/> User Loads Applied Unit Value	Free	Free	Free	Free	Free	Free	Load	Load
For Strength Analysis								
For Buckling Analysis								

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Strain Actual (Computed Properties Tab)

Deformation	
Strain X	0.0012
Strain Y	0.0012

Design-To Strain

$$\begin{aligned} \epsilon_x^{Actual} &= \epsilon_x^T \\ \epsilon_x^{Design-To} &= \epsilon_x^{Actual} - \epsilon_x^T \\ &= 0.0 \end{aligned}$$

Design-To Force

$$\begin{aligned} N_x^{Design-To} &= A_{11} \cancel{\epsilon_x^{Design-To}} + A_{12} \cancel{\epsilon_y^{Design-To}} \\ &= 0.0 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx,xx	Ny,yy	Nxy,xy	Mx,xx	My,yy	Mxy,xy	Qx	Qy
Virtual Loads								
Design-to Loads								
Design-to Deformation	0	0	0	0	0	0		



Ex 7 – Applied ΔT , Partially Constrained



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"

Thermal Load Set #201 "Load Set 201"

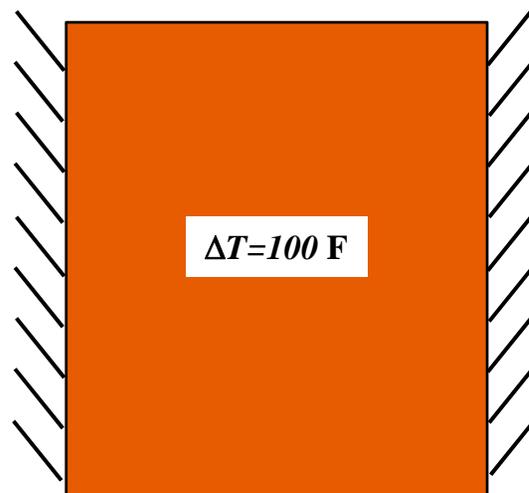
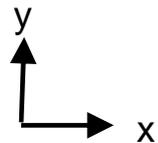
Ref Temp 100 Temp 200

Pressure TT Grad 0

FEA Loads - Projects Only

User Loads Applied Unit Value

	Nx, ex	Ny, ey	Nbz, ybz	Mx, vx	My, vy	Mbz, ybz	Qx	Qy
For Strength Analysis	Constrained	Free	Free	Free	Free	Free	Load	Load
For Buckling Analysis								



What will the loads look like?
Positive, negative or zero?

Ex 7 -Applied ΔT Partially Constrained



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

Ref Temp: 100 Temp: 200
 Pressure: TT Grad: 0

	Nx, <i>ex</i>	Ny, <i>ey</i>	Nxy, <i>xy</i>	Mx, <i>ix</i>	My, <i>iy</i>	Mxy, <i>ixy</i>	Qx	Qy
Applied Unit Value	Constraine	Free	Free	Free	Free	Free	Load	Load
For Strength Analysis								
For Buckling Analysis								

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, <i>ex</i>	Ny, <i>ey</i>	Nxy, <i>xy</i>	Mx, <i>ix</i>	My, <i>iy</i>	Mxy, <i>ixy</i>	Qx	Qy
Virtual Loads	-1.200	0	0	0	0	0	0	0
Design-to Loads	-1.200	0	0	0	0	0	0	0
Design-to Deformation	-0.0012	3.5999999E-04	0	0	0	0		



Ex 7 –Applied ΔT Partially Constrained



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

Ref Temp: 100 Temp: 200
 Pressure: TT Grad: 0

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Applied Unit Value	Constrained	Free	Free	Free	Free	Free	Load	Load
For Strength Analysis								
For Buckling Analysis								

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, ϵ_x	My, ϵ_y	Mxy, ϵ_{xy}	Qx	Qy
Virtual Loads	-1200	0	0	0	0	0	0	0
Design-to Loads	-1200	0	0	0	0	0	0	0
Design-to Deformation	-0.0012	3.599999E-04	0	0	0	0		

Ex 7 –Applied ΔT Partially Constrained



Input (Per Load Case)

***ULTIMATE-THERMAL** Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

Ref Temp	100	Temp	200
Pressure		TT Grad	0
Nx, ex	Constrained	Ny, ey	Free
Nxy, yxy	Free	Mx, ix	Free
My, iy	Free	Mxy, ixy	Free
Qx	Load	Qy	Load

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Strain Actual (Computed Properties Tab)

Deformation	
Strain X	0
Strain Y	0.00156

$$\begin{aligned} \epsilon_y^{Actual} &= \epsilon_y^T + \nu \epsilon_x^T \\ &= 0.00156 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ex	Ny, ey	Nxy, yxy	Mx, ix	My, iy	Mxy, ixy	Qx	Qy
Virtual Loads	-1200	0	0	0	0	0	0	0
Design-to Loads	-1200	0	0	0	0	0	0	0
Design-to Deformation	-0.0012	3.599999E-04	0	0	0	0		

Ex 7 –Applied ΔT Partially Constrained



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

Ref Temp	100	Temp	200				
Pressure		TT Grad	0				
Nx, ex	Ny, ey	Nxy, yxy	Mx, ix	My, iy	Mxy, ixy	Qx	Qy
Constrained	Free	Free	Free	Free	Free	Load	Load

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Strain Actual (Computed Properties Tab)

Deformation	
Strain X	0
Strain Y	0.00156

$$\begin{aligned} \epsilon_y^{Actual} &= \epsilon_y^T + \nu \epsilon_x^T \\ &= 0.00156 \end{aligned}$$

Design-To Strain

$$\begin{aligned} \epsilon_x^{Actual} &= \epsilon_x^T \\ \epsilon_x^{Design-To} &= \cancel{\epsilon_x^{Actual}} - \epsilon_x^T \\ &= -0.0012 \end{aligned}$$

$$\begin{aligned} \epsilon_y^{Design-To} &= \epsilon_y^{Actual} - \epsilon_y^T \\ \epsilon_y^{Design-To} &= (0.00156) - (0.0012) \\ &= 0.00036 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ex	Ny, ey	Nxy, yxy	Mx, ix	My, iy	Mxy, ixy	Qx	Qy
Virtual Loads	-1200	0	0	0	0	0	0	0
Design-to Loads	-1200	0	0	0	0	0	0	0
Design-to Deformation	-0.0012	3.599999E-04	0	0	0	0		

Ex 7 –Applied ΔT Partially Constrained



Input (Per Load Case)

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

Nx, ex	Ny, ey	Nxy, yxy	Mx, ix	My, iy	Mxy, ixy	Qx	Qy
Constrained	Free	Free	Free	Free	Free	Load	Load

Ref Temp: 100 Temp: 200
 Pressure: TT Grad: 0

Thermal Strain

$$\begin{aligned} \epsilon_x^T &= \epsilon_y^T = \alpha \Delta T \\ &= (12 \times 10^{-6})(100) \\ &= 0.0012 \end{aligned}$$

Design-To Force

$$\begin{aligned} N_x^{Design-To} &= A_{11} \epsilon_x^{Design-To} + A_{12} \epsilon_y^{Design-To} \\ &= (1.0989 \times 10^6)(-0.0012) + (0.3)(1.0989 \times 10^6)(0.00036) \\ &= -1200 \end{aligned}$$

Strain Actual (Computed Properties Tab)

Deformation	
Strain X	0
Strain Y	0.00156

$$\begin{aligned} \epsilon_y^{Actual} &= \epsilon_y^T + \nu \epsilon_x^T \\ &= 0.00156 \end{aligned}$$

Design-To Strain

$$\begin{aligned} \epsilon_x^{Actual} &= \epsilon_x^T \\ \epsilon_x^{Design-To} &= \cancel{\epsilon_x^{Actual}} - \epsilon_x^T \\ &= -0.0012 \end{aligned}$$

$$\begin{aligned} \epsilon_y^{Design-To} &= \epsilon_y^{Actual} - \epsilon_y^T \\ \epsilon_y^{Design-To} &= (0.00156) - (0.0012) \\ &= 0.00036 \end{aligned}$$

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx, ex	Ny, ey	Nxy, yxy	Mx, ix	My, iy	Mxy, ixy	Qx	Qy
Virtual Loads	-1200	0	0	0	0	0	0	0
Design-to Loads	-1200	0	0	0	0	0	0	0
Design-to Deformation	-0.0012	3.599999E-04	0	0	0	0		

Ex 8 – Thru-Thickness ΔT , Edges Free



Input (Per Load Case) $\Delta T = 1000$ F

ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

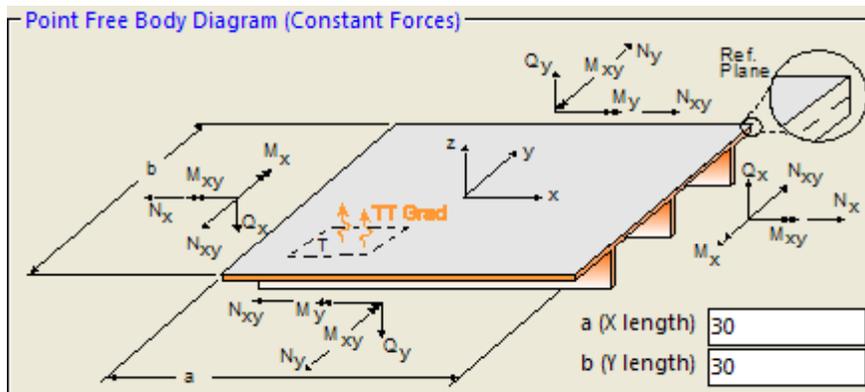
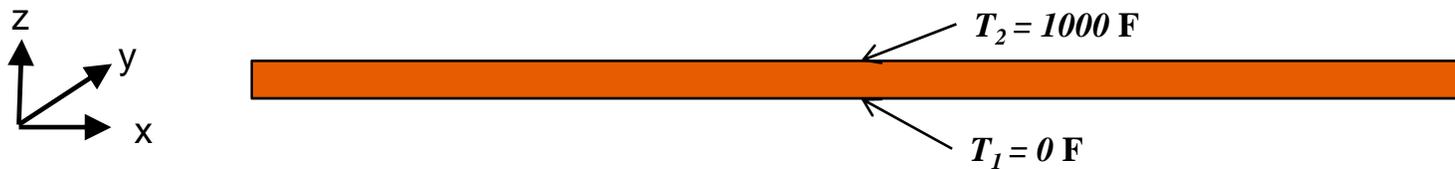
FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis
 For Buckling Analysis

	Nx, ex	Ny, ey	Nxy, yxy	Mx, ex	My, ey	Mxy, xxy	Qx	Qy
	Free	Free	Free	Free	Free	Free	Load	Load

Ref Temp: 100 Temp: 100
 Pressure: TT Grad: 1000

What will the strains look like?



Ex 8 – Thru-Thickness ΔT , Edges Free



Input (Per Load Case)

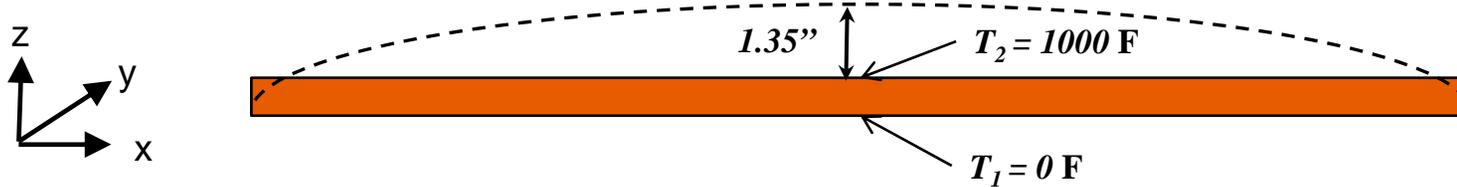
ULTIMATE-THERMAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"
 FEA Loads - Projects Only
 User Loads

Applied Unit Value: For Strength Analysis, For Buckling Analysis

	Nx,ex	Ny,ey	Nxy,xyy	Mx,xx	My,xy	Mxy,xyy	Qx	Qy
	Free	Free	Free	Free	Free	Free	Load	Load

Ref Temp: 100 Temp: 100
 Pressure: TT Grad: 1000



Deformation

Strain X		-0.0006
Strain Y		-0.0006
Curvature X		-0.012
Curvature Y		-0.012
Midspan Deflection		1.35

Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: BUCKLING

	Nx,ex	Ny,ey	Nxy,xyy	Mx,xx	My,xy	Mxy,xyy	Qx	Qy
Virtual Loads								
Design-to Loads								
Design-to Deformation	0	0	0	0	0	0		

Ex 9 – Panel Pressure



Input (Per Load Case)

LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

For Strength Analysis

For Buckling Analysis

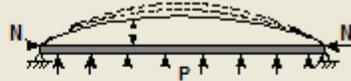
	N_x, ex	N_y, ey	N_{xy}, yxy	M_x, ex	M_y, ey	M_{xy}, xxy	Q_x	Q_y
	Free	Free	Free	Free	Free	Free	Load	Load

Ref Temp Temp

Pressure TT Grad

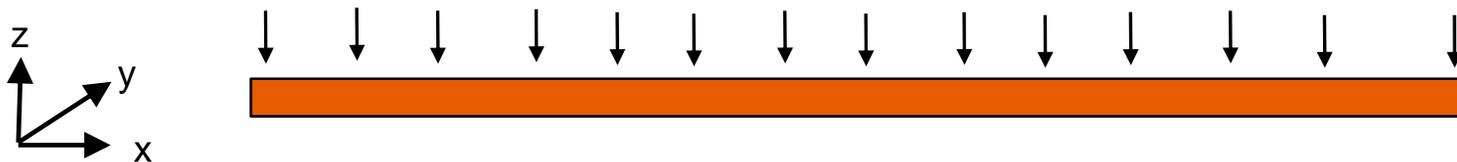
Superimposed Loads

Panel Pressure
 Beam-Column Moments

Initial Imperfection

Zero Out FEA Computed Moments



Ex 9 – Panel Pressure



Input (Per Load Case)

LIMIT-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)

Mechanical Load Set #101 "Load Set 101"
 Thermal Load Set #201 "Load Set 201"

FEA Loads - Projects Only
 User Loads Applied Unit Value

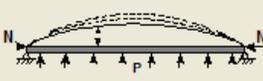
For Strength Analysis
 For Buckling Analysis

Nx,εx	Ny,εy	Nxy,γxy	Mx,εx	My,εy	Mxy,εxy	Qx	Qy
Free	Free	Free	Free	Free	Free	Load	Load

Ref Temp Temp
 Pressure -100 TT Grad

Superimposed Loads

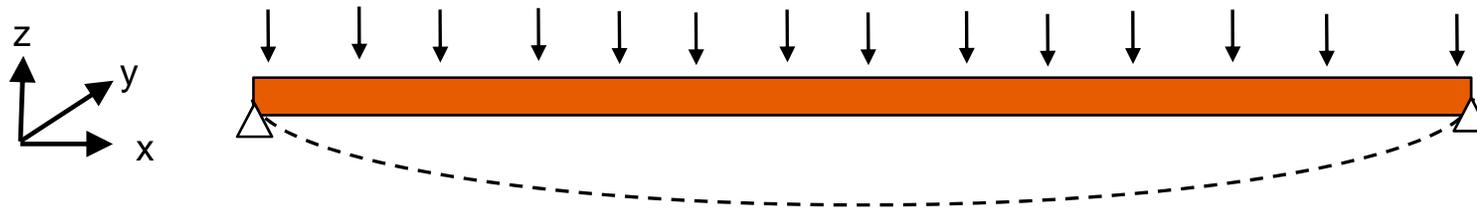
Panel Pressure
 Beam-Column Moments

Initial Imperfection

Zero Out FEA Computed Moments
 SIMPLE Boundary Condition

	Mx	My	Qx	Qy
MidSpan	4309.657	4309.657	0	0
EdgeCntr	0	0	-997.5873	-997.5873



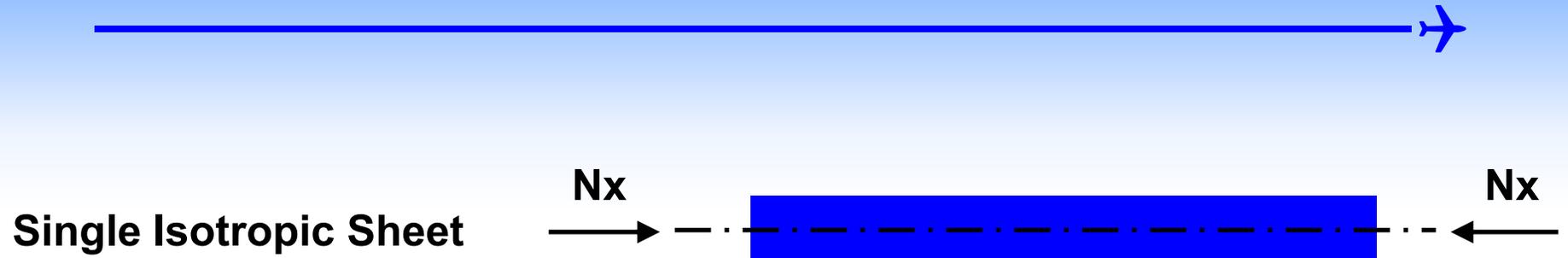
Free Body Diagram Output (Controlling Factored Loadcase)

Controlling Analysis Load: STRENGTH

Virtual Loads	Nx,εx	Ny,εy	Nxy,γxy	Mx,εx	My,εy	Mxy,εxy	Qx	Qy
Design-to Loads	0	0	0	4309.66	4309.66	0	0	0
Design-to Deformation	0	0	0	3.620112	3.620112	0		

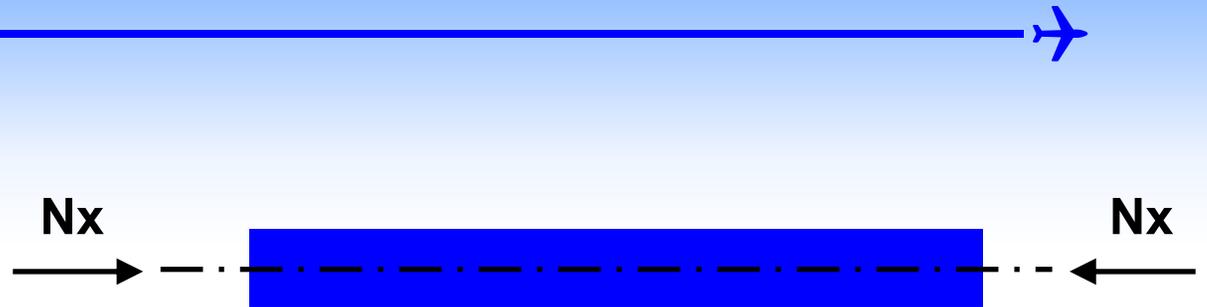


Panel Edge Loading



Panel Edge Loading

Single Isotropic Sheet



B Matrix = 0
No Membrane-Bending
Coupling

$$\begin{Bmatrix} \mathbf{N} \\ \mathbf{M} \end{Bmatrix} = \begin{bmatrix} \mathbf{A} & \mathbf{0} \\ \mathbf{0} & \mathbf{D} \end{bmatrix} \begin{Bmatrix} \boldsymbol{\varepsilon} \\ \boldsymbol{\kappa} \end{Bmatrix}$$



Panel Edge Loading

Single Isotropic Sheet



B Matrix = 0
No Membrane-Bending
Coupling

$$\begin{Bmatrix} \mathbf{N} \\ \mathbf{M} \end{Bmatrix} = \begin{bmatrix} \mathbf{A} & \mathbf{0} \\ \mathbf{0} & \mathbf{D} \end{bmatrix} \begin{Bmatrix} \boldsymbol{\varepsilon} \\ \boldsymbol{\kappa} \end{Bmatrix}$$

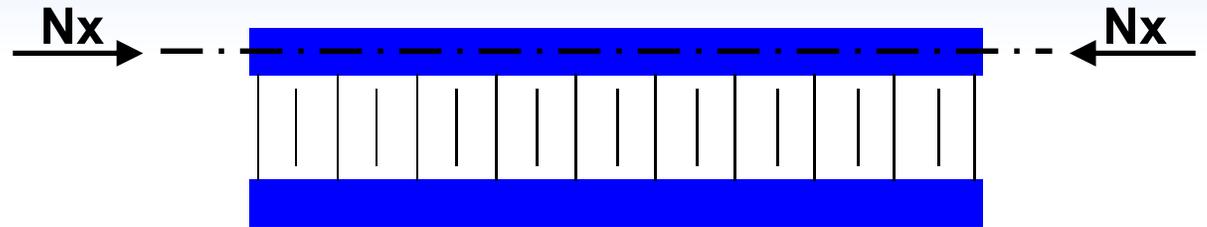
$$\mathbf{N} = \mathbf{A}\boldsymbol{\varepsilon}$$

$$\mathbf{M} = \mathbf{D}\boldsymbol{\kappa}$$



Panel Edge Loading

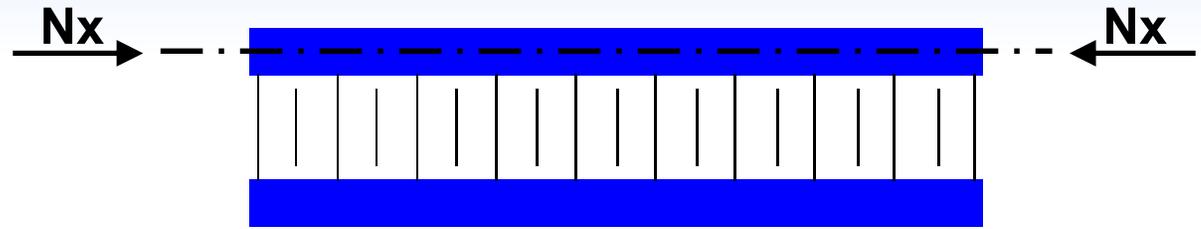
Symmetric Honeycomb Sandwich
(Note Reference Plane)



Panel Edge Loading



Symmetric Honeycomb Sandwich
(Note Reference Plane)



B Matrix $\neq 0$
Membrane-bending
Coupling is present

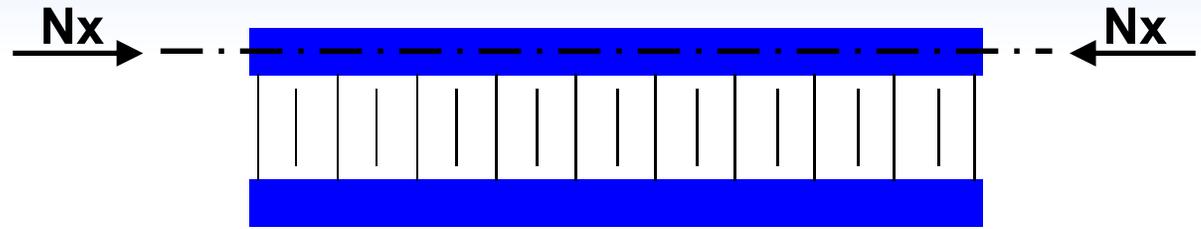
$$\begin{Bmatrix} N \\ M \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} \epsilon \\ \kappa \end{Bmatrix}$$



Panel Edge Loading



Symmetric Honeycomb Sandwich
(Note Reference Plane)



B Matrix $\neq 0$
Membrane-bending
Coupling is present

$$\begin{Bmatrix} N \\ M \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} \epsilon \\ \kappa \end{Bmatrix}$$

$$N = A\epsilon + B\kappa$$

$$M = B\epsilon + D\kappa$$



Free Body Diagram Math



Calculated by
HyperSizer

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$



Free Body Diagram Math



$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{Bmatrix}$$

Calculated by HyperSizer

“Knowns”



Free Body Diagram Math



“Unknowns”

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix}$$

=

Calculated by
HyperSizer

$$\begin{bmatrix} A & B \\ B & D \end{bmatrix}$$

“Knowns”

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{Bmatrix}$$

Free Body Diagram Math



“Unknowns”

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix}$$

=

Calculated by
HyperSizer

$$\begin{bmatrix} A & B \\ B & D \end{bmatrix}$$

“Knowns”

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{Bmatrix}$$

Unknowns on left, Knowns on right



Free Body Diagram Math – FEM Import



$$\left\{ \right\} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{bmatrix} \left\{ \begin{array}{c} \mathbf{N}_x \\ \mathbf{N}_y \\ \mathbf{N}_{xy} \\ \mathbf{M}_x \\ \mathbf{M}_y \\ \mathbf{M}_{xy} \end{array} \right\}$$

FORCES



Free Body Diagram Math – FEM Import



STRAINS

$$\left\{ \begin{array}{c} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{array} \right\}$$

=

$$\left[\begin{array}{cc} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{array} \right]$$

FORCES

$$\left\{ \begin{array}{c} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{array} \right\}$$



Free Body Diagram Math – FEM Import



STRAINS

$$\left\{ \begin{array}{c} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{array} \right\} =$$

Inverted Matrix

$$\left[\begin{array}{cc} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{array} \right]^{-1}$$

FORCES

$$\left\{ \begin{array}{c} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{array} \right\}$$

Free Body Diagram Math – FEM Import



STRAINS

Inverted Matrix

FORCES

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{Bmatrix} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{bmatrix}^{-1} \begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix}$$

$$\epsilon_x = A^{-1}_{11} N_x + A^{-1}_{12} N_y + \dots$$



Free Body Diagram Math – FEM Import



STRAINS

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{Bmatrix} =$$

Inverted Matrix

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{bmatrix}^{-1}$$

6x6

FORCES

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix}$$

$$\epsilon_x = A^{-1}_{11} N_x + A^{-1}_{12} N_y + \dots$$



Free Body Diagram Math – FEM Import



STRAINS

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{Bmatrix} =$$

Inverted Matrix

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{bmatrix}^{-1}$$

6x6

FORCES

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix}$$

Free Body Diagram Math – FEM Import



$$\begin{array}{c} \mathbf{STRAINS} \\ \left\{ \begin{array}{c} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{array} \right\} = \begin{array}{c} \text{Inverted Matrix} \\ \left[\begin{array}{cc} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{array} \right]^{-1} \\ \mathbf{6x6} \end{array} \begin{array}{c} \mathbf{FORCES} \\ \left\{ \begin{array}{c} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{array} \right\} \end{array}$$

When coupling HyperSizer with a FEM, the FEA computed forces are imported to compute panel strains and curvatures this way. (At the reference plane)



FBD Math – Workspace Loads



Specified Strain

	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Applied Unit Value	Deformation ▾	Constrained ▾	Constrained ▾	Constrained ▾	Constrained ▾	Constrained ▾
For Strength Analysis	0.01					
For Buckling Analysis	0.01					

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$



FBD Math – Workspace Loads



Specified Strain

	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Applied Unit Value	Deformation ▾	Constrained ▾	Constrained ▾	Constrained ▾	Constrained ▾	Constrained ▾
For Strength Analysis	0.01					
For Buckling Analysis	0.01					

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$

The value 0.01 in the table above is circled in orange and has an arrow pointing to the top element of the strain vector on the right, which is also circled in orange.



FBD Math – Workspace Loads

Specified Strain



	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, α_x	M_y, α_y	M_{xy}, α_{xy}
Applied Unit Value	Deformation	Constrained	Constrained	Constrained	Constrained	Constrained
For Strength Analysis	0.01					
For Buckling Analysis	0.01					

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} 0.01 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \end{Bmatrix}$$



FBD Math – Workspace Loads

Specified Strain



	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, α_x	M_y, α_y	M_{xy}, α_{xy}
Applied Unit Value	Deformation	Constrained	Constrained	Constrained	Constrained	Constrained
For Strength Analysis	0.01					
For Buckling Analysis	0.01					

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} 0.01 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \end{Bmatrix}$$

$$N_x = A_{11} \epsilon_x + A_{12} + 0.0$$

$$N_y = A_{21} \epsilon_x + A_{22} + 0.0$$



FBD Math – Workspace Loads



Specified Load

	Nx, ex	Ny, ey	Nxy, γxy	Mx, rx	My, ry	Mxy, rxy
Applied Unit Value	Load ▾	Constrained ▾				
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$



FBD Math – Workspace Loads

Specified Load



	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Applied Unit Value	Load	Constrained	Constrained	Constrained	Constrained	Constrained
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$

N_x is now known, ϵ_x is unknown



FBD Math – Workspace Loads

Specified Load

	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Applied Unit Value	Load	Constrained	Constrained	Constrained	Constrained	Constrained
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} \epsilon_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A' & B' \\ B' & D' \end{bmatrix} \begin{Bmatrix} N_x \\ \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$

Switch N_x and ϵ_x - Rearrange ABD



FBD Math – Workspace Loads



Specified Load

	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, ϵ_x	M_y, ϵ_y	M_{xy}, ϵ_{xy}
Applied Unit Value	Load	Constrained	Constrained	Constrained	Constrained	Constrained
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} \epsilon_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A' & B' \\ B' & D' \end{bmatrix} \begin{Bmatrix} -100 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \end{Bmatrix}$$



FBD Math – Workspace Loads



Virtual Loads

	Nx, ex	Ny, ey	Nxy, yxy	Mx, ex	My, ey	Mxy, exy
Applied Unit Value	Load	Constrained	Constrained	Constrained	Constrained	Constrained
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} \epsilon_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A' & B' \\ B' & D' \end{bmatrix} \begin{Bmatrix} N_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{Bmatrix}$$

Controlling Analysis Load: STRENGTH	Nx, ex	Ny, ey	Nxy, yxy	Mx, ex	My, ey	Mxy, exy
Virtual Loads	0	-31	0	0	0	0
Design-to Loads	-100	-31	0	0	0	0
Design-to Deformation	-4.351252E-05	0	0	0	0	0



FBD Math – Workspace Loads



Virtual Loads

	Nx, ex	Ny, ey	Nxy, yxy	Mx, ex	My, ey	Mxy, exy
Applied Unit Value	Load	Constrained	Constrained	Constrained	Constrained	Constrained
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} \epsilon_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A' & B' \\ B' & D' \end{bmatrix} \begin{Bmatrix} N_x \\ \epsilon_y \\ \epsilon_{xy} \\ K_x \\ K_y \\ K_{xy} \end{Bmatrix}$$

Controlling Analysis Load: STRENGTH	Nx, ex	Ny, ey	Nxy, yxy	Mx, ex	My, ey	Mxy, exy
Virtual Loads	0	-31	0	0	0	0
Design-to Loads	-100	-31	0	0	0	0
Design-to Deformation	-4.351252E-05		0	0	0	0



FBD Math – Workspace Loads



Virtual Loads

	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, κ_x	My, κ_y	Mxy, κ_{xy}
Applied Unit Value	Load	Constrained	Constrained	Constrained	Constrained	Constrained
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} \epsilon_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A' & B' \\ B' & D' \end{bmatrix} \begin{Bmatrix} N_x \\ \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$

Controlling Analysis Load: STRENGTH	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, κ_x	My, κ_y	Mxy, κ_{xy}
Virtual Loads	0	-31	0	0	0	0
Design-to Loads	-100	-31	0	0	0	0
Design-to Deformation	-4.351252E-05		0	0	0	0

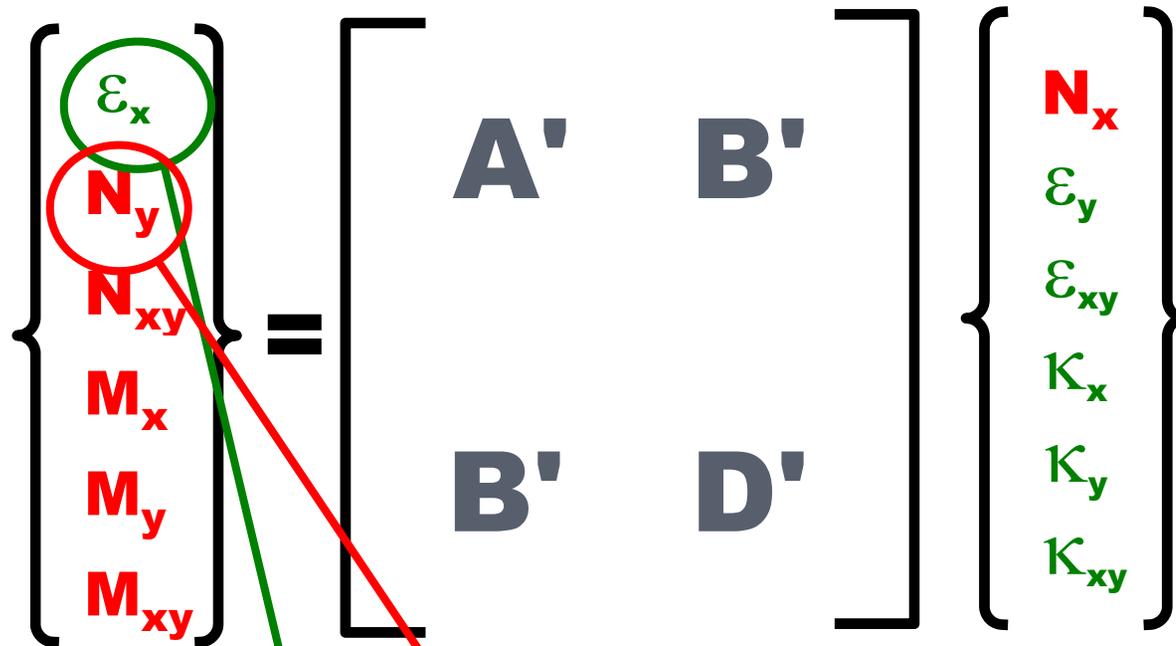


FBD Math – Workspace Loads



Virtual Loads

$$N_y = A'_{21} N_x + A'_{22} \epsilon_y + \dots$$



Controlling Analysis Load: STRENGTH	Nx, ex	Ny, ey	Nxy, yxy	Mx, ex	My, ey	Mxy, exy
Virtual Loads	0	-31	0	0	0	0
Design-to Loads	-100	-31	0	0	0	0
Design-to Deformation	-4.351252E-05		0	0	0	0



Free Boundary Conditions



Applied Unit Value	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
For Strength Analysis	Load	Free	Constrained	Constrained	Constrained	Constrained
For Buckling Analysis	-100					
	-100					

$$\begin{Bmatrix} \epsilon_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A' & B' \\ B' & D' \end{bmatrix} \begin{Bmatrix} N_x \\ \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$

Controlling Analysis Load: STRENGTH	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Virtual Loads						
Design-to Loads	-100	0	0	0	0	0
Design-to Deformation	-5.212941E-05	1.616012E-05	0	0	0	0



Free Boundary Conditions



	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, κ_x	My, κ_y	Mxy, κ_{xy}
Applied Unit Value	Load	Free	Constrained	Constrained	Constrained	Constrained
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} \epsilon_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A' & B' \\ B' & D' \end{bmatrix} \begin{Bmatrix} N_x \\ \epsilon_y \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$

Controlling Analysis Load: STRENGTH	Nx, ϵ_x	Ny, ϵ_y	Nxy, γ_{xy}	Mx, κ_x	My, κ_y	Mxy, κ_{xy}
Virtual Loads						
Design-to Loads	-100	0	0	0	0	0
Design-to Deformation	-5.212941E-05	1.616012E-05	0	0	0	0



Free Boundary Conditions



Applied Unit Value	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Load	▼	Free ▼	Constrained ▼	Constrained ▼	Constrained ▼	Constrained ▼
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A'' & B'' \\ B'' & D'' \end{bmatrix} \begin{Bmatrix} N_x \\ N_y = 0 \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$

The diagram shows a matrix equation for boundary conditions. On the left, a column vector contains ϵ_x , ϵ_y , N_{xy} , M_x , M_y , and M_{xy} . A green circle highlights ϵ_x and ϵ_y . In the center is a 2x2 matrix with A'' and B'' in the top row, and B'' and D'' in the bottom row. On the right, another column vector contains N_x , $N_y = 0$, ϵ_{xy} , κ_x , κ_y , and κ_{xy} . A red circle highlights N_x and $N_y = 0$. A red arrow points from the $N_y = 0$ element to the ϵ_y element.

Controlling Analysis Load: STRENGTH	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Virtual Loads						
Design-to Loads	-100	0	0	0	0	0
Design-to Deformation	-5.212941E-05	1.616012E-05	0	0	0	0



Free Boundary Conditions



Applied Unit Value	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Load	▼	Free ▼	Constrained ▼	Constrained ▼	Constrained ▼	Constrained ▼
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A'' & B'' \\ B'' & D'' \end{bmatrix} \begin{Bmatrix} N_x \\ N_y = 0 \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$

Controlling Analysis Load: STRENGTH	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Virtual Loads						
Design-to Loads	-100	0	0	0	0	0
Design-to Deformation	-5.212941E-05	1.616012E-05	0	0	0	0



Free Boundary Conditions



Applied Unit Value	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Load	▼	Free ▼	Constrained ▼	Constrained ▼	Constrained ▼	Constrained ▼
For Strength Analysis	-100					
For Buckling Analysis	-100					

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} A'' & B'' \\ B'' & D'' \end{bmatrix} \begin{Bmatrix} N_x \\ N_y = 0 \\ \epsilon_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{Bmatrix}$$

Note: double prime 6x6 matrix

Controlling Analysis Load: STRENGTH	N_x, ϵ_x	N_y, ϵ_y	N_{xy}, γ_{xy}	M_x, κ_x	M_y, κ_y	M_{xy}, κ_{xy}
Virtual Loads						
Design-to Loads	-100	0	0	0	0	0
Design-to Deformation	-5.212941E-05	1.616012E-05	0	0	0	0



Analyses are Independent of Loads Source



HyperSizer Failure Analyses



Analyses are Independent of Loads Source



User Input by hand, (typed-in loads).
Very convenient interactive tool

Variables		FBD		Object Lc
Input (Per Load Case)				
ULTIMATE-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)				
<input checked="" type="radio"/> Mechanical Load Set #101 "Load Set 101"				
<input type="radio"/> Thermal Load Set #201 "Load Set 201"				
<input type="radio"/> FEA Loads - Projects Only				
<input checked="" type="radio"/> User Loads				
Applied Unit Value	Nx,ex	Ny,ey	Nxy,xy	
	Load	Constrained	Deformation	
For Strength Analysis	-2000		0.00042	
For Buckling Analysis	-2000		0.00036	



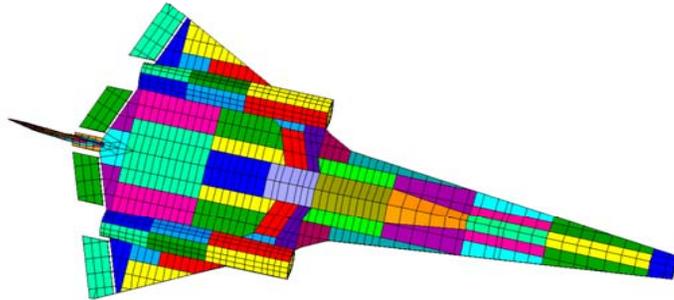
HyperSizer Failure Analyses



Analyses are Independent of Loads Source



FEA Computed Loads



User Input by hand, (typed-in loads).
Very convenient interactive tool

Variables	FBD	Object Lc	
Input (Per Load Case)			
ULTIMATE-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)			
<input checked="" type="radio"/> Mechanical Load Set #101 "Load Set 101"			
<input type="radio"/> Thermal Load Set #201 "Load Set 201"			
<input type="radio"/> FEA Loads - Projects Only			
<input checked="" type="radio"/> User Loads			
Applied Unit Value	Nx,ex	Ny,ey	Nxy,xy
For Strength Analysis	-2000		0.00042
For Buckling Analysis	-2000		0.00036

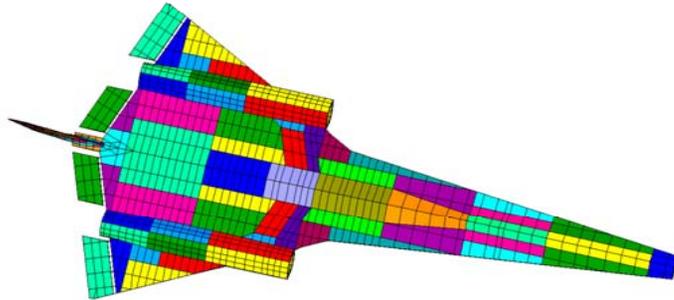
HyperSizer Failure Analyses



Analyses are Independent of Loads Source



FEA Computed Loads



User Input by hand, (typed-in loads).
Very convenient interactive tool

Variables	FBD	Object Lc
Input (Per Load Case)		
ULTIMATE-MECHANICAL Load Case #1 "one" (Mechanical Set #101, Thermal Set #201)		
<input checked="" type="radio"/> Mechanical Load Set #101 "Load Set 101" <input type="radio"/> Thermal Load Set #201 "Load Set 201"		
<input type="radio"/> FEA Loads - Projects Only <input checked="" type="radio"/> User Loads		
Applied Unit Value	Nx,ex	Ny,ey
For Strength Analysis	Load	Constrained
For Buckling Analysis	-2000	0.00042
	-2000	0.00036

Other Sources Using HyperSizer's Object Model Interface:

- Loads from spreadsheets



- Loads from a larger company software design system





Appendix

Appendix I: ABD of Isotropic Plate



- Reduced stiffness matrix Q
 - Plane stress constitutive equation
 - In-plane properties E , ν , & G

$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} \frac{E}{1-\nu^2} & \frac{\nu E}{1-\nu^2} & 0 \\ \frac{\nu E}{1-\nu^2} & \frac{E}{1-\nu^2} & 0 \\ 0 & 0 & G_{12} \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix} = \mathbf{Q} \vec{\varepsilon}$$

Appendix I: ABD of Isotropic Plate



- Integrate Q over the single layer
 - $h_0 = -t/2, h_1 = t/2$

$$A_{ij} = \sum_{k=1}^n Q_{ij}(\theta_k)(h_k - h_{k-1}) = \boxed{Qt}$$

$$B_{ij} = \sum_{k=1}^n Q_{ij}(\theta_k)(h_k^2 - h_{k-1}^2)/2 = Q\left(\frac{t^2}{4} - \frac{t^2}{4}\right)/2 = \boxed{0}$$

$$D_{ij} = \sum_{k=1}^n Q_{ij}(\theta_k)(h_k^3 - h_{k-1}^3)/3 = Q\left(\frac{t^3}{8} - \frac{t^3}{8}\right)/3 = \boxed{Q\frac{t^3}{12}}$$

Appendix I: ABD of Isotropic Plate



- Final ABD

$$\begin{bmatrix} N_x \\ N_y \\ N_s \\ M_x \\ M_y \\ M_s \end{bmatrix} = \begin{bmatrix} \frac{Et}{1-\nu^2} & \frac{\nu Et}{1-\nu^2} & 0 & 0 & 0 & 0 \\ \frac{\nu Et}{1-\nu^2} & \frac{Et}{1-\nu^2} & 0 & 0 & 0 & 0 \\ 0 & 0 & G_{12}t & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{Et^3}{12(1-\nu^2)} & \frac{\nu Et^3}{12(1-\nu^2)} & 0 \\ 0 & 0 & 0 & \frac{\nu Et^3}{12(1-\nu^2)} & \frac{Et^3}{12(1-\nu^2)} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{G_{12}t^3}{12} \end{bmatrix} \begin{bmatrix} \varepsilon_x^o \\ \varepsilon_y^o \\ \gamma_{xy}^o \\ \kappa_x \\ \kappa_y \\ \kappa_z \end{bmatrix}$$

Appendix II: Iso Effective Elastic Constants



- Goal is reduce ABD relation of isotropic plate to the forms:
 - N_x load, N_y free, N_{xy} free, M free

$$\varepsilon_x = \frac{N_x}{tE_x^{eff}}$$

$$\varepsilon_y = -\nu_{xy}^{eff} \varepsilon_x$$

Appendix II: Iso Effective Elastic Constants



- Start with isotropic ABD

$$\begin{bmatrix} N_x \\ N_y \\ N_s \\ M_x \\ M_y \\ M_s \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} & 0 & 0 & 0 & 0 \\ A_{12} & A_{22} & 0 & 0 & 0 & 0 \\ 0 & 0 & A_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & D_{11} & D_{12} & 0 \\ 0 & 0 & 0 & D_{12} & D_{22} & 0 \\ 0 & 0 & 0 & 0 & 0 & D_{33} \end{bmatrix} \begin{bmatrix} \varepsilon_x^o \\ \varepsilon_y^o \\ \gamma_{xy}^o \\ \kappa_x \\ \kappa_y \\ \kappa_z \end{bmatrix}$$

Appendix II: Iso Effective Elastic Constants



- Invert

$$\begin{bmatrix} \varepsilon_x^o \\ \varepsilon_y^o \\ \gamma_{xy}^o \\ \kappa_x \\ \kappa_y \\ \kappa_z \end{bmatrix} = \begin{bmatrix} \frac{A_{22}}{A_{11}A_{22} - A_{12}^2} & \frac{-A_{12}}{A_{11}A_{22} - A_{12}^2} & 0 & 0 & 0 & 0 \\ \frac{-A_{12}}{A_{11}A_{22} - A_{12}^2} & \frac{A_{11}}{A_{11}A_{22} - A_{12}^2} & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{A_{33}} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{D_{22}}{-D_{12}^2 + D_{11}D_{22}} & \frac{-D_{12}}{-D_{12}^2 + D_{11}D_{22}} & 0 \\ 0 & 0 & 0 & \frac{-D_{12}}{-D_{12}^2 + D_{11}D_{22}} & \frac{D_{11}}{-D_{12}^2 + D_{11}D_{22}} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{D_{33}} \end{bmatrix} \begin{bmatrix} N_x \\ N_y \\ N_s \\ M_x \\ M_y \\ M_s \end{bmatrix}$$

Appendix II: Iso Effective Elastic Constants



- N_x load, N_y free, N_{xy} free, M free

$$\begin{aligned}\epsilon_x^o &= \frac{A_{22}}{A_{11}A_{22} - A_{12}^2} N_x \\ &= \frac{N_x}{E_x^{eff}}\end{aligned}$$

$$\begin{aligned}\epsilon_y^o &= \frac{-A_{12}}{A_{11}A_{22} - A_{12}^2} N_x \\ &= \frac{-A_{12}}{A_{11}A_{22} - A_{12}^2} \frac{A_{11}A_{22} - A_{12}^2}{A_{22}} \epsilon_x^o \\ &= \frac{-A_{12}}{A_{22}} \epsilon_x^o \\ &= -\nu_{xy}^{eff} \epsilon_x^o\end{aligned}$$

Appendix III: ABD⁻¹ of Isotropic Plate



- Inverted ABD – see Appendix II

$$\begin{bmatrix} \varepsilon_x^o \\ \varepsilon_y^o \\ \gamma_{xy}^o \\ \kappa_x \\ \kappa_y \\ \kappa_z \end{bmatrix} = \begin{bmatrix} \frac{A_{22}}{A_{11}A_{22} - A_{12}^2} & \frac{-A_{12}}{A_{11}A_{22} - A_{12}^2} & 0 & 0 & 0 & 0 \\ \frac{-A_{12}}{A_{11}A_{22} - A_{12}^2} & \frac{A_{11}}{A_{11}A_{22} - A_{12}^2} & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{A_{33}} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{D_{22}}{-D_{12}^2 + D_{11}D_{22}} & \frac{-D_{12}}{-D_{12}^2 + D_{11}D_{22}} & 0 \\ 0 & 0 & 0 & \frac{-D_{12}}{-D_{12}^2 + D_{11}D_{22}} & \frac{D_{11}}{-D_{12}^2 + D_{11}D_{22}} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{D_{33}} \end{bmatrix} \begin{bmatrix} N_x \\ N_y \\ N_s \\ M_x \\ M_y \\ M_s \end{bmatrix}$$

Appendix III: ABD⁻¹ of Isotropic Plate



- Simplify inverse matrix terms

$$A_{11}^{-1} = \frac{A_{22}}{A_{11}A_{22} - A_{12}^2} = \frac{Et}{\frac{(Et)^2 - (Etv)^2}{1-\nu^2}} = \frac{1-\nu^2}{Et(1-\nu^2)} = \frac{1}{Et}$$

$$A_{22}^{-1} = \frac{1}{Et}$$

$$A_{12}^{-1} = \frac{-\nu}{Et}$$

$$A_{33}^{-1} = \frac{1}{Gt}$$

$$\begin{bmatrix} \varepsilon_x^o \\ \varepsilon_y^o \\ \gamma_{xy}^o \\ \kappa_x \\ \kappa_y \\ \kappa_z \end{bmatrix} = \begin{bmatrix} A_{11}^{-1} & A_{12}^{-1} & 0 & 0 & 0 & 0 \\ A_{12}^{-1} & A_{22}^{-1} & 0 & 0 & 0 & 0 \\ 0 & 0 & A_{33}^{-1} & 0 & 0 & 0 \\ 0 & 0 & 0 & D_{11}^{-1} & D_{12}^{-1} & 0 \\ 0 & 0 & 0 & D_{12}^{-1} & D_{22}^{-1} & 0 \\ 0 & 0 & 0 & 0 & 0 & D_{33}^{-1} \end{bmatrix} \begin{bmatrix} N_x \\ N_y \\ N_s \\ M_x \\ M_y \\ M_s \end{bmatrix}$$





Extra

Isotropic Plate Stiffness



□ Compliance

$$\begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix} = \begin{bmatrix} \frac{1}{E} & \frac{-\nu}{E} & 0 \\ \frac{-\nu}{E} & \frac{1}{E} & 0 \\ 0 & 0 & \frac{1}{G_{12}} \end{bmatrix} \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix}$$

Isotropic Plate Stiffness



□ Compliance

□ Stiffness

$$\begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix} = \begin{bmatrix} \frac{1}{E} & \frac{-\nu}{E} & 0 \\ \frac{-\nu}{E} & \frac{1}{E} & 0 \\ 0 & 0 & \frac{1}{G_{12}} \end{bmatrix} \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix}$$



$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} \frac{E}{1-\nu^2} & \frac{\nu E}{1-\nu^2} & 0 \\ \frac{\nu E}{1-\nu^2} & \frac{E}{1-\nu^2} & 0 \\ 0 & 0 & G_{12} \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix}$$

Isotropic Plate Stiffness



□ Compliance

□ Stiffness

$$\begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix} = \begin{bmatrix} \frac{1}{E} & \frac{-\nu}{E} & 0 \\ \frac{-\nu}{E} & \frac{1}{E} & 0 \\ 0 & 0 & \frac{1}{G_{12}} \end{bmatrix} \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix}$$



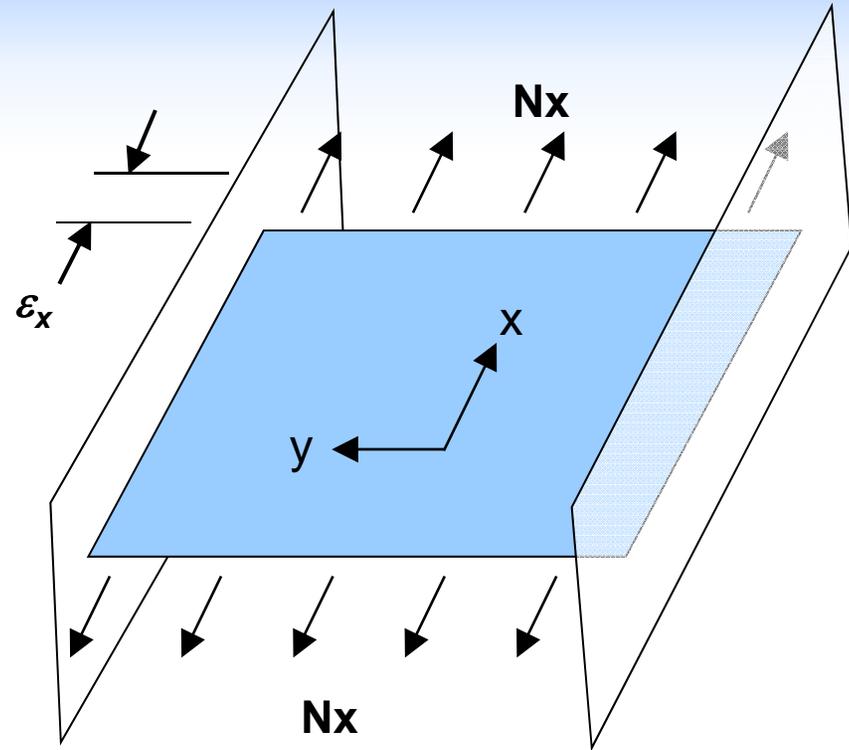
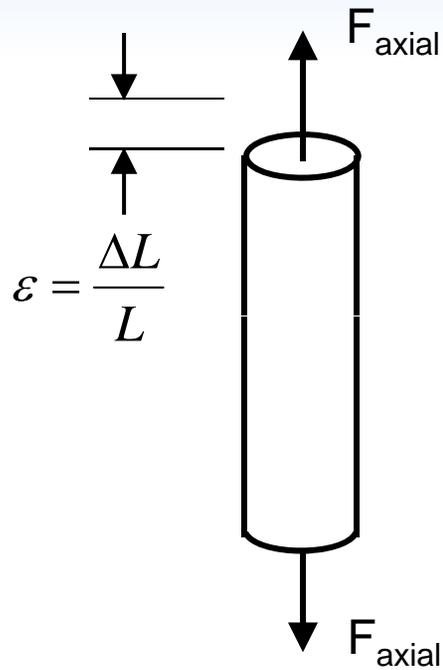
$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} \frac{E}{1-\nu^2} & \frac{\nu E}{1-\nu^2} & 0 \\ \frac{\nu E}{1-\nu^2} & \frac{E}{1-\nu^2} & 0 \\ 0 & 0 & G_{12} \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \gamma_{12} \end{bmatrix}$$

Poisson term
for plates

$$\frac{1}{1-\nu^2}$$



Effective Modulus ($\epsilon_y = 0$)



$$\sigma = E \epsilon$$

$$\sigma_x = \left(\frac{E}{1-\nu^2} \right) \epsilon_x + \cancel{\nu \left(\frac{E}{1-\nu^2} \right) \epsilon_y}$$

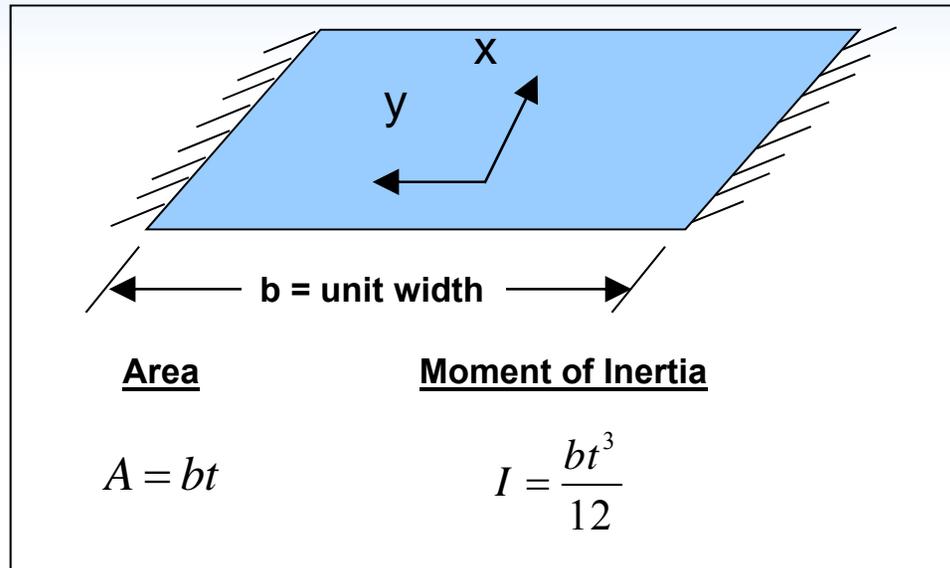
$$\sigma_x = \left(\frac{E}{1-\nu^2} \right) \epsilon_x = E^* \epsilon_x$$

Convert Stress → Line Load



$$N_x = \sigma_x t$$

$$\sigma_x = E^* \varepsilon_x$$



$$M_x' = M_x t$$

$$M_x = E^* I \kappa$$

Membrane

Unit Force

$$\begin{aligned} N_x^* &= \left(\frac{E}{1-\nu^2} \right) \varepsilon t \\ &= \frac{Et}{1-\nu^2} \varepsilon_x \\ &= A_{11} \varepsilon_x \end{aligned}$$

Stiffness

$$A_{11} = \frac{Et}{1-\nu^2}$$

Bending

Unit Moment

$$\begin{aligned} M_x' &= \left(\frac{E}{1-\nu^2} \right) I \kappa t \\ &= \frac{Et^3}{12(1-\nu^2)} \kappa \\ &= D_{11} \kappa \end{aligned}$$

Bending Stiffness

$$D_{11} = \frac{Et^3}{12(1-\nu^2)}$$



Membrane Coupling Relationships



$$\begin{bmatrix} N_x \\ N_y \\ N_{xy} \end{bmatrix} = \begin{bmatrix} \frac{Et}{1-\nu^2} & \frac{\nu Et}{1-\nu^2} & 0 \\ \frac{\nu Et}{1-\nu^2} & \frac{Et}{1-\nu^2} & 0 \\ 0 & 0 & Gt \end{bmatrix} \begin{bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy} \end{bmatrix} \quad \left| \quad \begin{bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy} \end{bmatrix} = \begin{bmatrix} \frac{1}{Et} & -\frac{\nu}{Et} & 0 \\ -\frac{\nu}{Et} & \frac{1}{Et} & 0 \\ 0 & 0 & \frac{1}{Gt} \end{bmatrix} \begin{bmatrix} N_x \\ N_y \\ N_{xy} \end{bmatrix}$$